

# An Introduction to the Wavelet Variance and Its Statistical Properties

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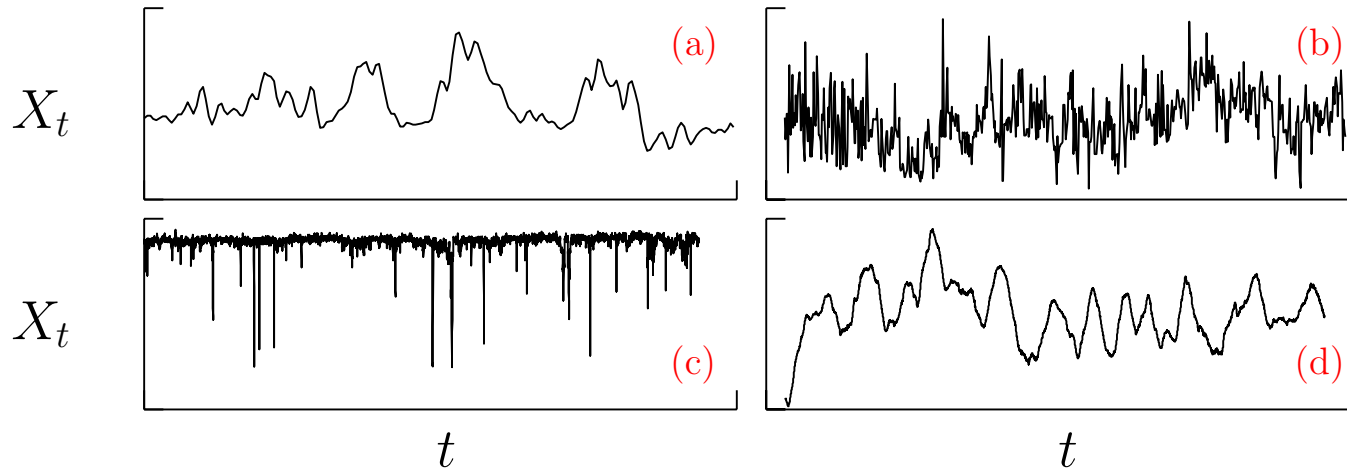
overheads for talk available at

<http://faculty.washington.edu/dbp/talks.html>

# Overview

- examples of time series to motivate discussion
- wavelet filters, wavelet coefficients & their interpretation
- decomposition of sample variance using wavelets
- theoretical wavelet variance for stochastic processes
  - stationary processes
  - nonstationary processes with stationary differences
- sampling theory for Gaussian processes with an example
- sampling theory for non-Gaussian processes with an example
- use on time series with time-varying statistical properties
- extensions: covariances, biased estimators, gappy series, fields
- summary

## Examples: Time Series $X_t$ Versus Time Index $t$



(a) subtidal sea levels (2 observations each day,  $N = 192$ )

(b) Nile River minima (annual,  $N = 663$ )

(c) surface albedo of arctic ice (25 meters,  $N = 8428$ )

(d) vertical shear in the ocean (0.1 meters,  $N = 4096$ )

- four series are visually different
- goal of time series analysis is to quantify these differences

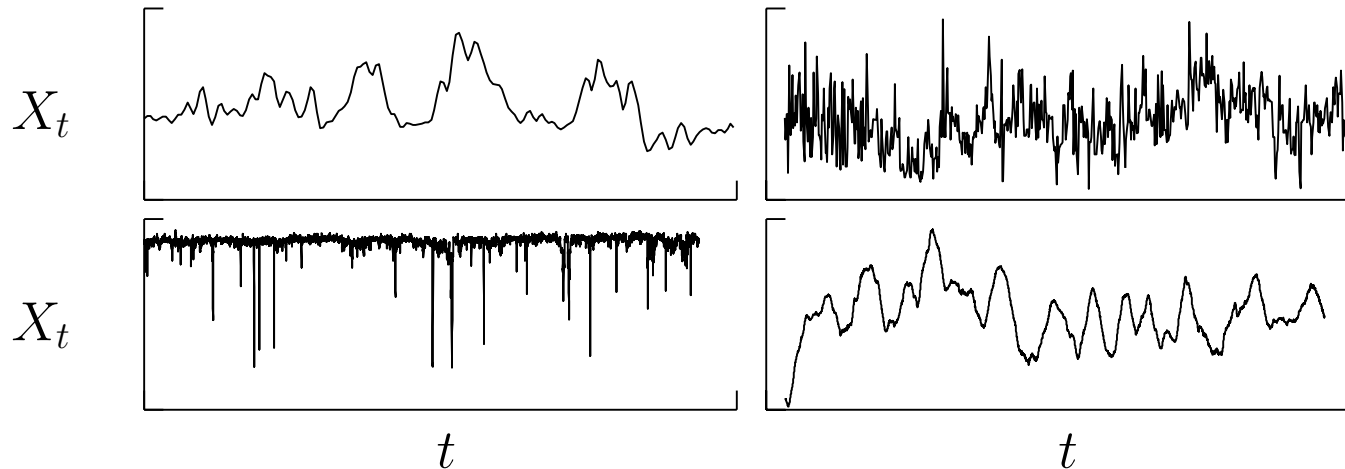
## Decomposing Sample Variance of Time Series

- one approach: quantify differences by analysis of variance
- let  $X_0, X_1, \dots, X_{N-1}$  represent time series with  $N$  values
- let  $\bar{X}$  denote sample mean of  $X_t$ 's:  $\bar{X} \equiv \frac{1}{N} \sum_{t=0}^{N-1} X_t$
- let  $\hat{\sigma}_X^2$  denote sample variance of  $X_t$ 's:

$$\hat{\sigma}_X^2 \equiv \frac{1}{N} \sum_{t=0}^{N-1} (X_t - \bar{X})^2$$

- idea is to decompose (analyze, break up)  $\hat{\sigma}_X^2$  into pieces that quantify how time series are different
- wavelet variance does analysis based upon differences between (possibly weighted) adjacent averages over 'scales'

## Examples Revisited: Notion of Scale



- scale  $\tau$  refers to the width of a time interval
- scale-based analysis looks at averages over intervals of width  $\tau$ :

$$\overline{X}_t(\tau) \equiv \frac{1}{\tau} \sum_{l=0}^{\tau-1} X_{t-l}$$

(variation: replace simple average above with weighted average)

- $\overline{X}_t(1) = X_t$  is scale 1 ‘average’, while  $\overline{X}_{N-1}(N) = \overline{X}$

## Wavelet Coefficients and Filters

- wavelet coefficients tell us about variations in adjacent averages
- use wavelet filter to create wavelet coefficients
- given  $X_0, X_1, \dots, X_{N-1}$ , define wavelet coefficients via

$$\widetilde{W}_{j,t} \equiv \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l \bmod N}, \quad t = 0, 1, \dots, N-1,$$

where  $\tilde{h}_{j,l}$  is a wavelet filter with  $L_j$  coefficients, and

$$X_{t-l \bmod N} = X_t, \quad 0 \leq t-l \leq N-1$$

$$X_{-1 \bmod N} = X_{N-1}$$

$$X_{-2 \bmod N} = X_{N-2} \text{ etc ('circularity')}$$

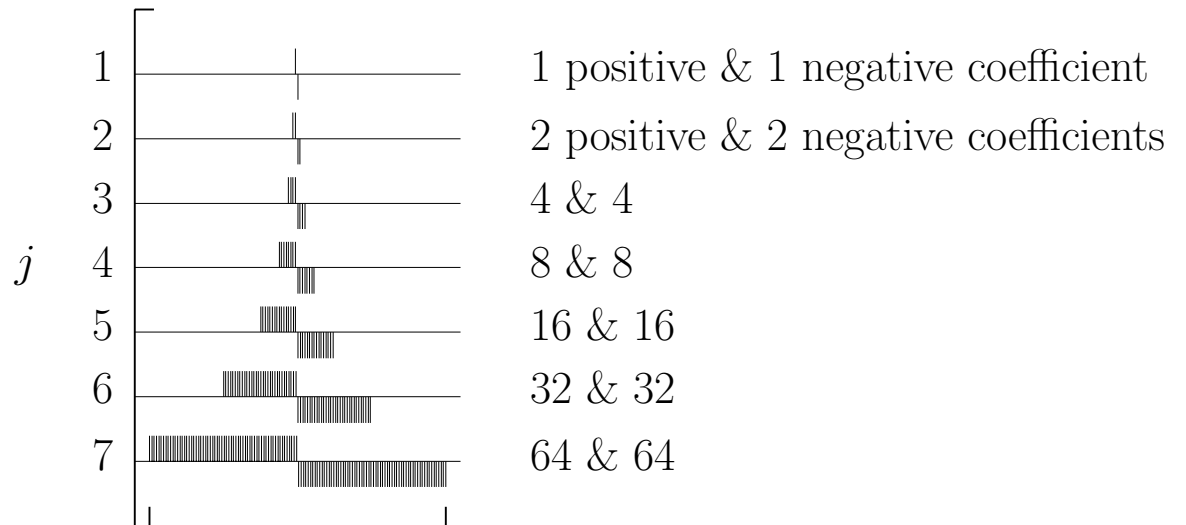
- index  $j$  specifies associated scale as  $\tau_j \equiv 2^{j-1}$ ,  $j = 1, 2, \dots$ ;  
i.e., scales are powers of two (1, 2, 4, 8, ...)

## Daubechies Wavelet Filters

- analysis of variance requires filter  $\tilde{h}_{1,l}$  of unit scale to satisfy certain conditions
- will use Daubechies wavelet filters with  $L_1$  coefficients, for which
  - $\sum_{l=0}^{L_1-1} \tilde{h}_{1,l} = 0$
  - $\sum_{l=0}^{L_1-1} \tilde{h}_{1,l}^2 = 1/2$
  - $\sum_{l=0}^{L_1-1} \tilde{h}_{1,l} \tilde{h}_{1,l+2k} = 0$  for nonzero integers  $k$
- $\tilde{h}_{j,l}$ 's for  $j > 1$  are 'stretched out' versions of  $\tilde{h}_{1,l}$
- $L_1$  must be even integer (2, 4, 6, ... )
- when  $L_1 = 2$ , filter is known as the Haar wavelet filter

## Example: Haar Wavelet Filters

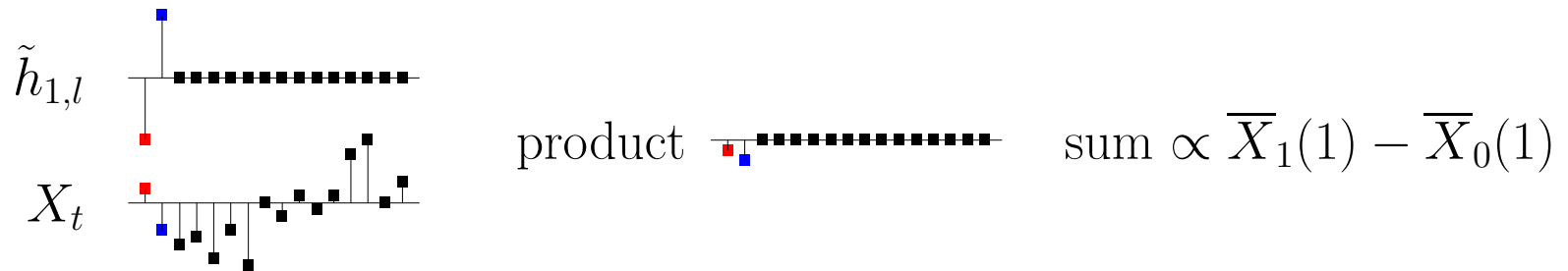
- Haar wavelet filters  $\tilde{h}_{j,l}$  for scales indexed by  $j = 1, \dots, 7$



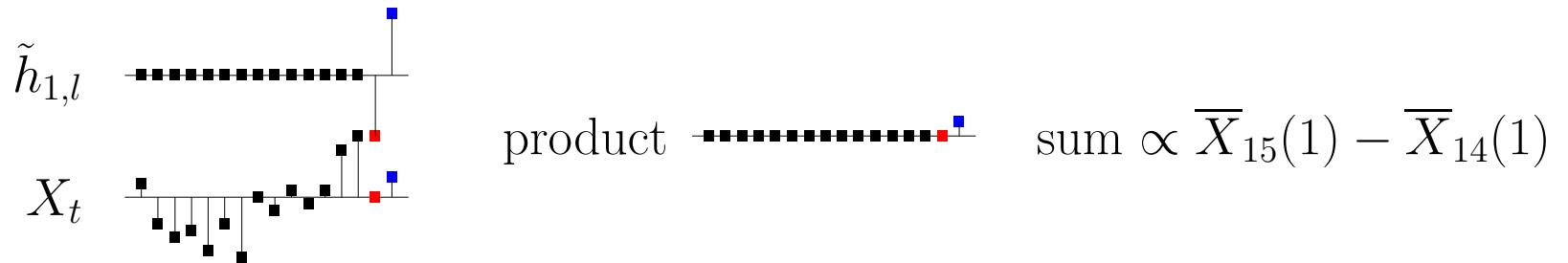


# Haar Wavelet Coefficients: I

- consider how  $\widetilde{W}_{1,1} = \sum_l \tilde{h}_{1,l} X_{1-l \bmod N}$  is formed ( $N = 16$ ):

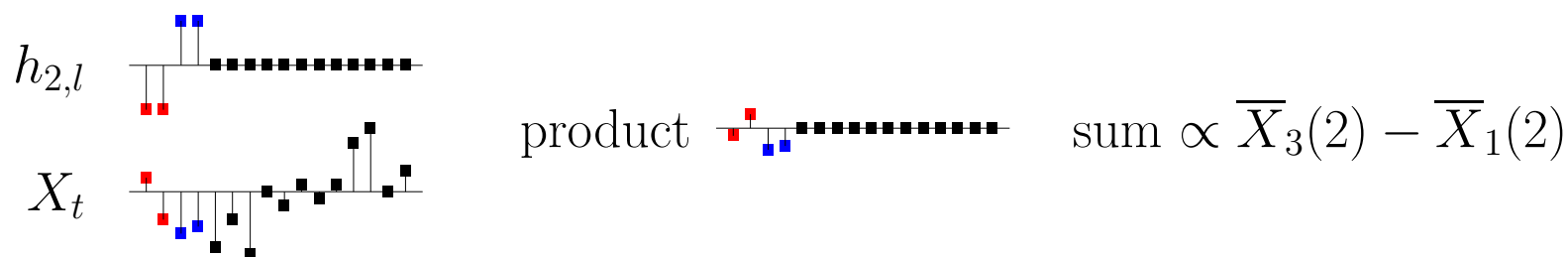


- similar interpretation for  $\widetilde{W}_{1,15} = \sum_l \tilde{h}_{1,l} X_{15-l \bmod N}$ :



## Haar Wavelet Coefficients: II

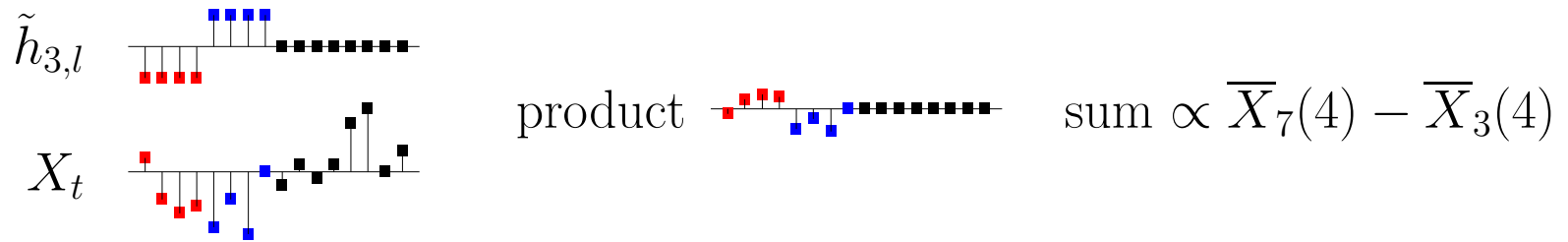
- now consider form of  $\widetilde{W}_{2,3} = \sum_l \tilde{h}_{2,l} X_{3-l \bmod N}$ :



- similar interpretation for  $\widetilde{W}_{2,4}, \widetilde{W}_{2,5}, \dots, \widetilde{W}_{2,15}$
- note:  $\widetilde{W}_{2,0}, \widetilde{W}_{2,1}$  and  $\widetilde{W}_{2,2}$  aren't proportional to differences of adjacent averages (called 'boundary' coefficients)

## Haar Wavelet Coefficients: III

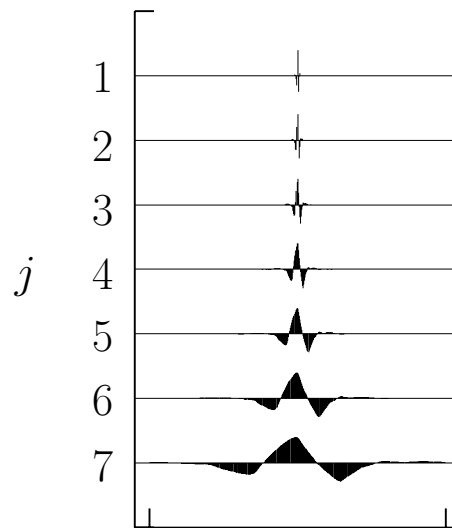
- $\widetilde{W}_{3,7} = \sum_l \tilde{h}_{3,l} X_{7-l \bmod N}$  takes the following form:



- Haar wavelet coefficients  $\widetilde{W}_{j,t}$  for scale  $\tau_j = 2^{j-1}$  proportional to  $\bar{X}_t(\tau_j) - \bar{X}_{t-\tau_j}(\tau_j)$ . i.e., to change in adjacent  $\tau_j$  averages
  - change measured by simple first difference
  - average is localized sample mean
  - if  $\widetilde{W}_{j,t}^2$  small, not much variation over scale  $\tau_j$
  - if  $\widetilde{W}_{j,t}^2$  large, lot of variation over scale  $\tau_j$

## Second Example: LA(8) Wavelet Filters

- as example of another wavelet filter, consider the Daubechies 'least asymmetric' filter of width 8 (denoted as LA(8))



- LA(8) wavelet coefficients proportional to difference between central weighted average and 2 surrounding weighted averages

## Empirical Wavelet Variance

- define empirical wavelet variance for scale  $\tau_j$  as

$$\tilde{\nu}_X^2(\tau_j) \equiv \frac{1}{N} \sum_{t=0}^{N-1} \widetilde{W}_{j,t}^2$$

- if  $N = 2^J$ , obtain analysis (decomposition) of sample variance:

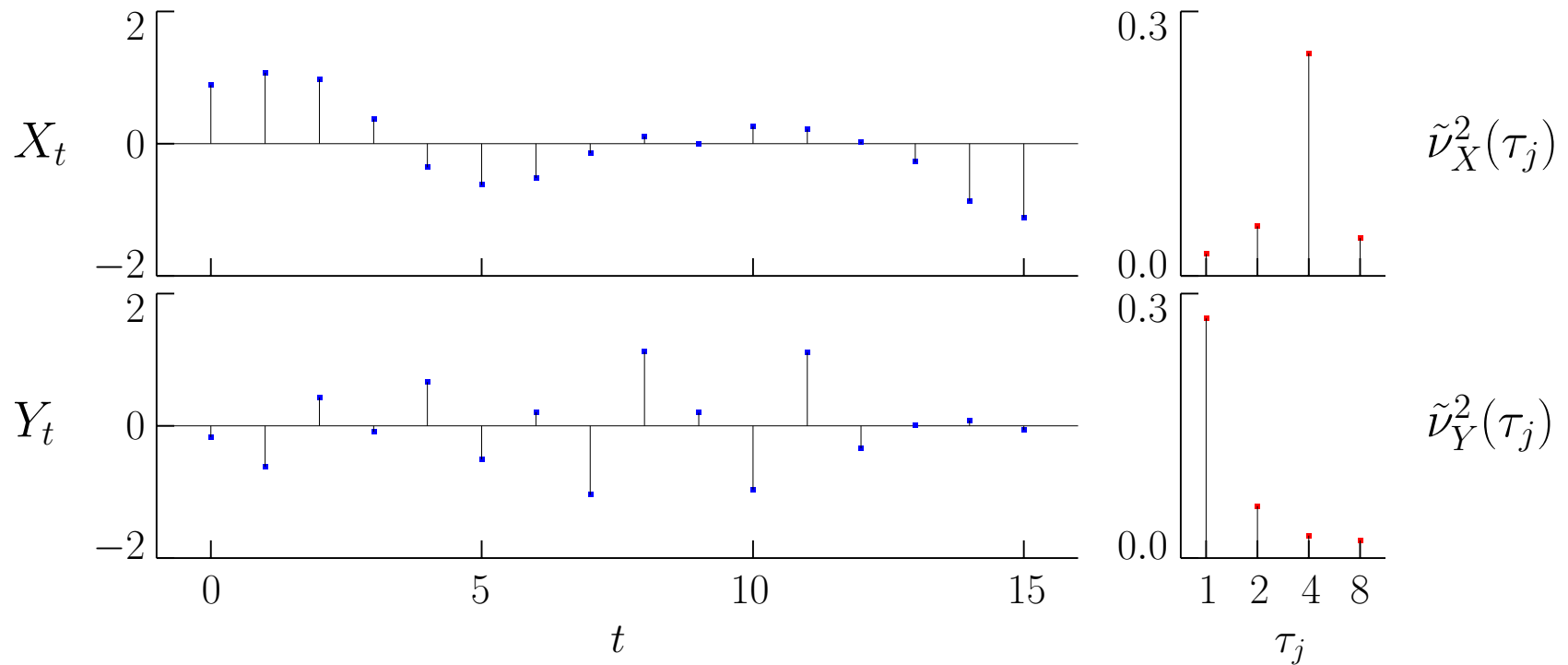
$$\hat{\sigma}_X^2 = \frac{1}{N} \sum_{t=0}^{N-1} (X_t - \bar{X})^2 = \sum_{j=1}^J \tilde{\nu}_X^2(\tau_j)$$

(if  $N$  not a power of 2, can still obtain an analysis of variance to a given level  $J_0$ , but have component due to ‘scaling’ filter)

- interpretation:  $\tilde{\nu}_X^2(\tau_j)$  is portion of  $\hat{\sigma}_X^2$  due to changes in averages over scale  $\tau_j$ ; i.e., ‘scale by scale’ analysis of variance

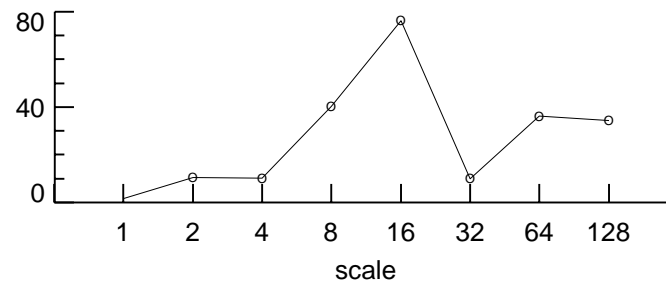
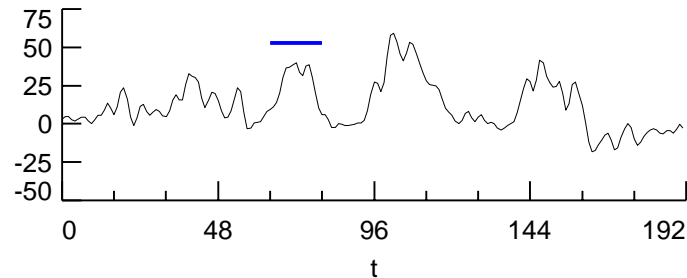
## Example of Empirical Wavelet Variance

- wavelet variances for time series  $X_t$  and  $Y_t$  of length  $N = 16$ , each with zero sample mean and same sample variance



## Second Example of Empirical Wavelet Variance

- top: subtidal sea level series  $X_t$  (blue line shows scale of 16)



- bottom: empirical wavelet variances  $\tilde{\nu}_X^2(\tau_j)$
- note: each  $\widetilde{W}_{j,t}$  associated with a portion of  $X_t$ , so  $\widetilde{W}_{j,t}^2$  versus  $t$  offers time-based decomposition of  $\tilde{\nu}_X^2(\tau_j)$

## Theoretical Wavelet Variance: I

- now assume  $X_t$  is a real-valued random variable (RV)
- let  $X_t, t \in \mathbb{Z}$  denote a stochastic process, i.e., collection of RVs indexed by ‘time’  $t$  (here  $\mathbb{Z}$  denotes the set of all integers)
- filter  $X_t$  to create new stochastic process:

$$\bar{W}_{j,t} \equiv \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l}, \quad t \in \mathbb{Z},$$

which should be contrasted with

$$\widetilde{W}_{j,t} \equiv \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l \bmod N}, \quad t = 0, 1, \dots, N-1$$



## Theoretical Wavelet Variance: II

- if  $Y$  is any RV, let  $E\{Y\}$  denote its expectation
- let  $\text{var}\{Y\}$  denote its variance:  $\text{var}\{Y\} \equiv E\{(Y - E\{Y\})^2\}$
- definition of time dependent wavelet variance:

$$\nu_{X,t}^2(\tau_j) \equiv \text{var}\{\overline{W}_{j,t}\},$$

with conditions on  $X_t$  so that  $\text{var}\{\overline{W}_{j,t}\}$  exists and is finite

- $\nu_{X,t}^2(\tau_j)$  depends on  $\tau_j$  and  $t$
- will focus on time independent wavelet variance

$$\nu_X^2(\tau_j) \equiv \text{var}\{\overline{W}_{j,t}\}$$

(can adapt theory to handle time varying situation)

- $\nu_X^2(\tau_j)$  well-defined for stationary & related processes, so let's review concept of stationarity

## Definition of a Stationary Process

- if  $U$  and  $V$  are two RVs, denote their covariance by

$$\text{cov}\{U, V\} = E\{(U - E\{U\})(V - E\{V\})\}$$

- stochastic process  $X_t$  called stationary if
  - $E\{X_t\} = \mu_X$  for all  $t$ , i.e., constant independent of  $t$
  - $\text{cov}\{X_t, X_{t+\tau}\} = s_{X,\tau}$ , i.e., depends on lag  $\tau$ , but not  $t$
- $s_{X,\tau}$ ,  $\tau \in \mathbb{Z}$ , is autocovariance sequence (ACVS)
- $s_{X,0} = \text{cov}\{X_t, X_t\} = \text{var}\{X_t\}$ ; i.e., variance same for all  $t$

## Example of a Stationary Process: White Noise

- simplest example of a stationary process is ‘white noise’
- process  $X_t$  said to be white noise if
  - it has a constant mean  $E\{X_t\} = \mu_X$
  - it has a constant variance  $\text{var}\{X_t\} = \sigma_X^2$
  - $\text{cov}\{X_t, X_{t+\tau}\} = 0$  for all  $t$  and nonzero  $\tau$ ; i.e., distinct RVs in the process are uncorrelated
- ACVS for white noise takes a very simple form:

$$s_{X,\tau} = \text{cov}\{X_t, X_{t+\tau}\} = \begin{cases} \sigma_X^2, & \tau = 0; \\ 0, & \text{otherwise.} \end{cases}$$

## Wavelet Variance for Stationary Processes

- for stationary processes, wavelet variance decomposes  $\text{var} \{X_t\}$ :

$$\sum_{j=1}^{\infty} \nu_X^2(\tau_j) = \text{var} \{X_t\}$$

(above result similar to one for sample variance)

- $\nu_X^2(\tau_j)$  is thus contribution to  $\text{var} \{X_t\}$  due to scale  $\tau_j$
- example: for a white noise process, have

$$\nu_X^2(\tau_j) = \frac{\text{var} \{X_t\}}{2^j} = \frac{\text{var} \{X_t\}}{2\tau_j},$$

so largest contribution to  $\text{var} \{X_t\}$  is at smallest scale  $\tau_1$

- note:  $\nu_X(\tau_j)$  has same units as  $X_t$ , which is important for interpretability

## Generalization to Certain Nonstationary Processes

- if  $L_1$  is properly chosen,  $\nu_X^2(\tau_j)$  well-defined for processes with stationary backward differences
- first order backward difference of  $X_t$  is process defined by

$$X_t^{(1)} = X_t - X_{t-1}$$

- second order backward difference of  $X_t$  is process defined by

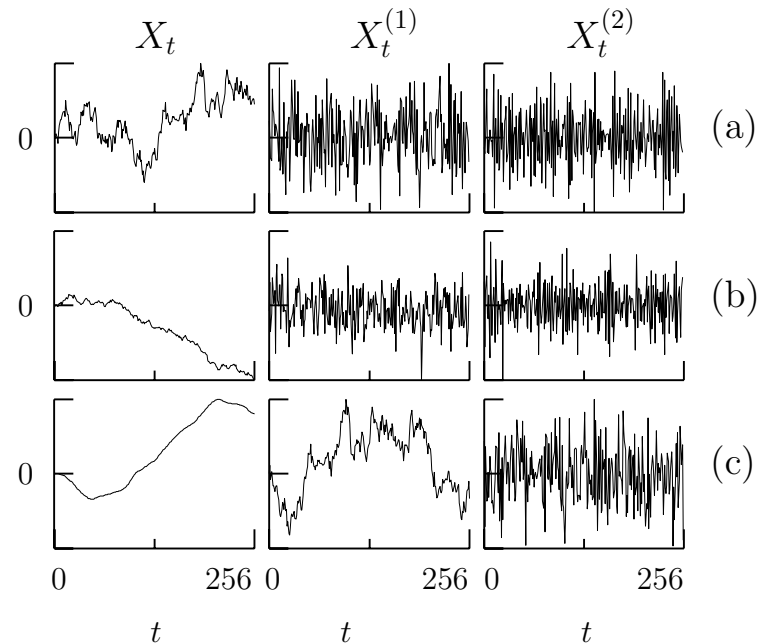
$$X_t^{(2)} = X_t^{(1)} - X_{t-1}^{(1)} = X_t - 2X_{t-1} + X_{t-2}$$

- $X_t$  has  $d$ th order stationary backward differences if

$$Y_t \equiv \sum_{k=0}^d \binom{d}{k} (-1)^k X_{t-k}$$

forms a stationary process ( $d$  is a nonnegative integer)

## Examples of Processes with Stationary Increments



- 1st column shows, from top to bottom, realizations from
  - (a) random walk:  $X_t = \sum_{u=1}^t \epsilon_t$ , &  $\epsilon_t$  is zero mean white noise
  - (b) like (a), but now  $\epsilon_t$  has mean of  $-0.2$
  - (c) random run:  $X_t = \sum_{u=1}^t Y_t$ , where  $Y_t$  is a random walk
- 2nd & 3rd columns show 1st & 2nd differences  $X_t^{(1)}$  and  $X_t^{(2)}$

## Wavelet Variance for Processes with Stationary Backward Differences

- suppose  $X_t$  nonstationary with  $d$ th order stationary differences
- if  $L_1 \geq 2d$ , then  $\nu_X^2(\tau_j)$  is well-defined & finite for all  $\tau_j$ , but now we have

$$\sum_{j=1}^{\infty} \nu_X^2(\tau_j) = \infty$$

- example: for a random walk process  $X_t = \sum_{u=1}^t \epsilon_u$ , have

$$\nu_X^2(\tau_j) = \frac{\text{var} \{\epsilon_t\}}{6} \left( \tau_j + \frac{1}{2\tau_j} \right)$$

with Haar wavelet, so  $\nu_X^2(\tau_j)$  increases as  $j$  increases

## Fractionally Differenced (FD) Processes: I

- as an example, consider wavelet variance for FD processes (Granger & Joyeux, 1980; Hosking, 1981)
- FD processes determined by 2 parameters  $-\infty < \delta < \infty$  &  $\sigma_\epsilon^2 > 0$  (relatively unimportant)
- let  $\text{FD}(\delta)$  refer to FD process with parameter  $\delta$
- if  $\delta < 1/2$ , FD process  $X_t$  is stationary, and, in particular,
  - reduces to white noise if  $\delta = 0$
  - has ‘long memory’ if  $\delta > 0$
  - is ‘antipersistent’ if  $\delta < 0$  (i.e.,  $\text{cov}\{X_t, X_{t+1}\} < 0$ )



## Fractionally Differenced (FD) Processes: II

- if  $\delta \geq 1/2$ , FD process  $X_t$  is nonstationary with  $d$ th order stationary backward differences  $Y_t$ 
  - here  $d = \lfloor \delta + 1/2 \rfloor$ , where  $\lfloor x \rfloor$  is integer part of  $x$
  - $Y_t$  is stationary FD( $\delta - d$ ) process

- if  $\delta = 1$ , FD process is the same as a random walk process

- at large scales, have

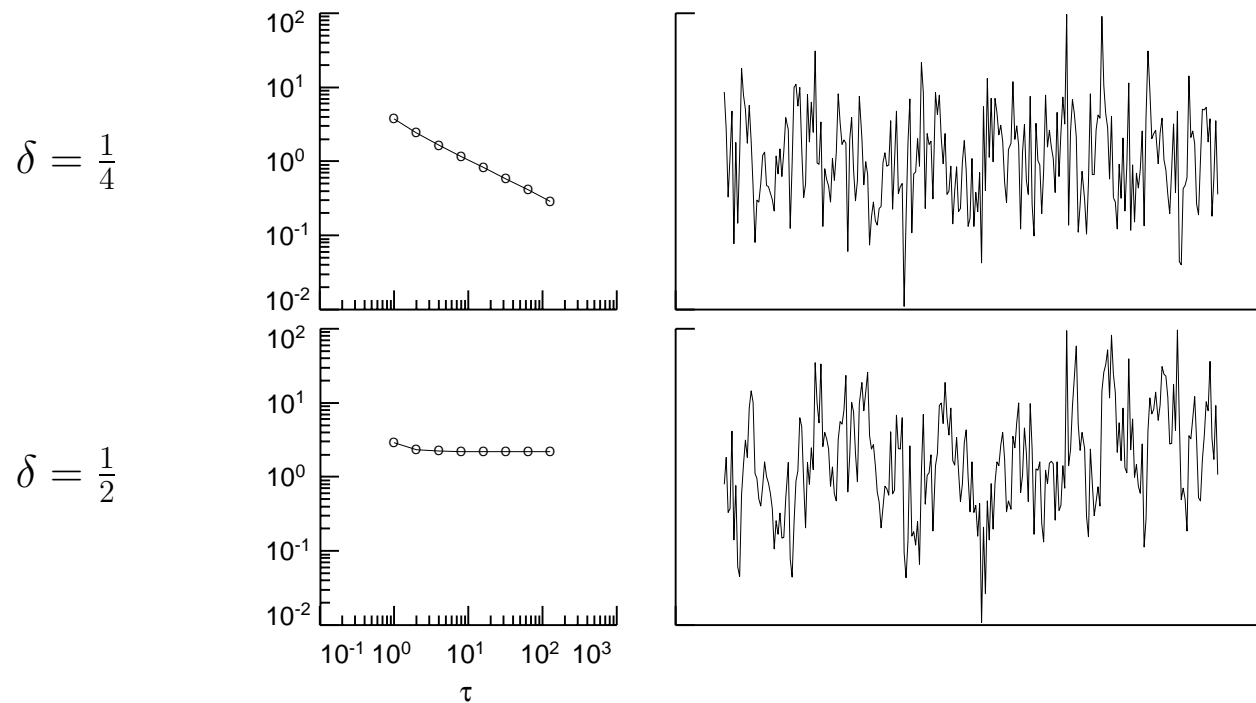
$$\nu_X^2(\tau_j) \approx C \tau_j^{2\delta-1}$$

- thus

$$\log(\nu_X^2(\tau_j)) \approx \log(C) + (2\delta - 1) \log(\tau_j),$$

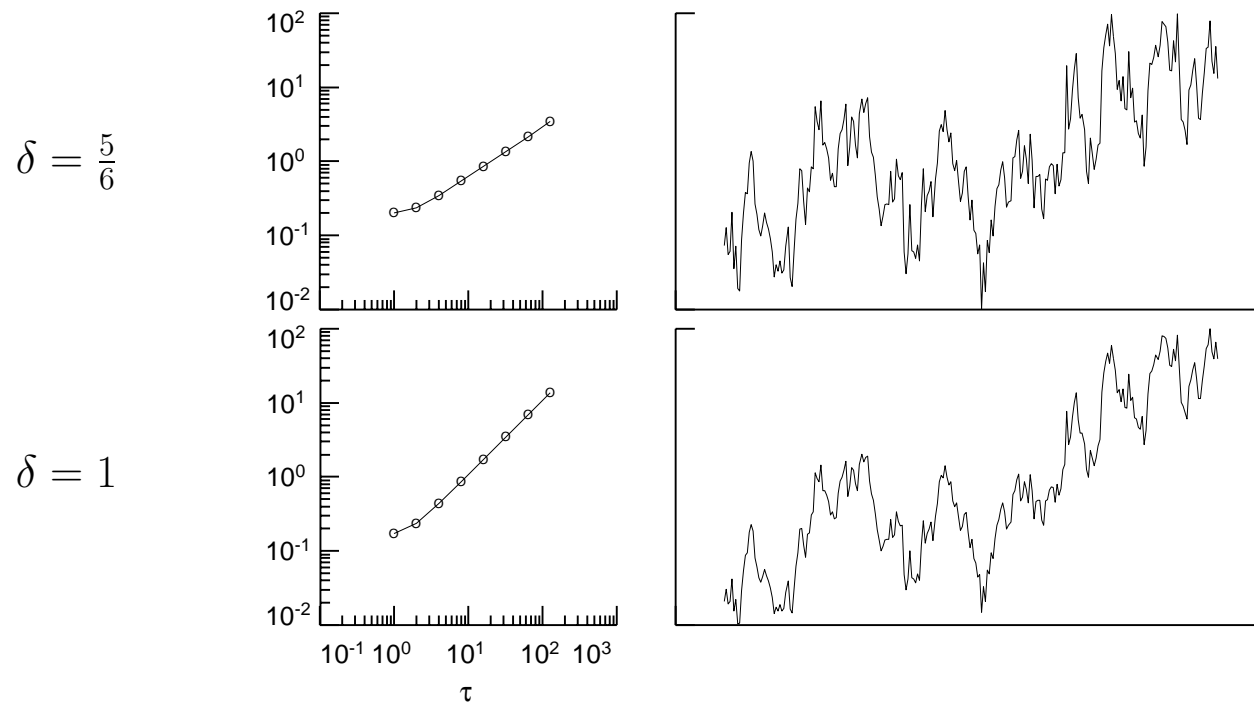
so a log/log plot of  $\nu_X^2(\tau_j)$  vs.  $\tau_j$  looks approximately linear with slope  $2\delta - 1$  for  $\tau_j$  large enough

## LA(8) Wavelet Variance for 2 FD Processes



- left-hand column:  $\nu_X^2(\tau_j)$  versus  $\tau_j$  based upon LA(8) wavelet
- right-hand: realization of length  $N = 256$  from each FD process (created via circulant embedding – details in Craigmile, 2003)

# LA(8) Wavelet Variance for 2 More FD Processes



- $\delta = \frac{5}{6}$  is Kolmogorov turbulence;  $\delta = 1$  is random walk
- note: positive slope indicates nonstationarity, while negative slope indicates stationarity

## Unbiased Estimator of Wavelet Variance: I

- given a realization of  $X_0, X_1, \dots, X_{N-1}$  from a process with  $d$ th order stationary differences, want to estimate  $\nu_X^2(\tau_j)$
- for wavelet filter such that  $L_1 \geq 2d$  and  $E\{\overline{W}_{j,t}\} = 0$ , have

$$\nu_X^2(\tau_j) = \text{var}\{\overline{W}_{j,t}\} = E\{\overline{W}_{j,t}^2\}$$

- can base estimator on squares of

$$\widetilde{W}_{j,t} \equiv \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l \bmod N}, \quad t = 0, 1, \dots, N-1$$

- recall that

$$\overline{W}_{j,t} \equiv \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l}, \quad t \in \mathbb{Z}$$

## Unbiased Estimator of Wavelet Variance: II

- comparing

$$\widetilde{W}_{j,t} = \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l \bmod N} \quad \text{with} \quad \overline{W}_{j,t} \equiv \sum_{l=0}^{L_j-1} \tilde{h}_{j,l} X_{t-l}$$

says that  $\widetilde{W}_{j,t} = \overline{W}_{j,t}$  if ‘mod  $N$ ’ not needed; this happens when  $L_j - 1 \leq t < N$

- if  $N - L_j \geq 0$ , unbiased estimator of  $\nu_X^2(\tau_j)$  is

$$\hat{\nu}_X^2(\tau_j) \equiv \frac{1}{N - L_j + 1} \sum_{t=L_j-1}^{N-1} \widetilde{W}_{j,t}^2 = \frac{1}{M_j} \sum_{t=L_j-1}^{N-1} \overline{W}_{j,t}^2,$$

where  $M_j \equiv N - L_j + 1$

## Statistical Properties of $\hat{\nu}_X^2(\tau_j)$ (Gaussian)

- suppose  $\{\overline{W}_{j,t}\}$  Gaussian with mean zero & ACVS  $s_{j,\tau}$   
(note: filtering tends to yield normality)
- suppose square summability condition holds:

$$A_j \equiv \sum_{\tau=-\infty}^{\infty} s_{j,\tau}^2 < \infty.$$

- can show  $\hat{\nu}_X^2(\tau_j)$  asymptotically normal with mean  $\nu_X^2(\tau_j)$  & large sample variance  $2A_j/M_j$
- $A_j$  finite if ACVS damps quickly to 0
- if  $A_j$  infinite, can usually correct by increasing  $L_1$
- conclusion: square integrability easy to satisfy
- Monte Carlo studies: large sample theory good if  $M_j \geq 128$

## Estimation of $A_j$

- in practical applications, need to estimate

$$A_j = \sum_{\tau=-\infty}^{\infty} s_{j,\tau}^2$$

- for large  $M_j$ , an approximately unbiased estimator is

$$\hat{A}_j \equiv \frac{\hat{s}_{j,0}^2}{2} + \sum_{\tau=1}^{M_j-1} \hat{s}_{j,\tau}^2,$$

where

$$\hat{s}_{j,\tau} \equiv \frac{1}{M_j} \sum_{t=L_j-1}^{N-1-|\tau|} \widetilde{W}_{j,t} \widetilde{W}_{j,t+|\tau|}$$

- Monte Carlo results:  $\hat{A}_j$  reasonably good for  $M_j \geq 128$

## Confidence Intervals (CIs) for $\nu_X^2(\tau_j)$

- for finite  $M_j$ , Gaussian-based CIs problematic: lower limit of CI can very well be negative
- can avoid by basing CIs on the assumption that

$$\hat{\nu}_X^2(\tau_j) = \frac{1}{M_j} \sum_{t=L_j-1}^{N-1} \widetilde{W}_{j,t}^2$$

has the same distribution as  $a\chi_\eta^2$ , i.e., a constant times a chi-square RV with  $\eta$  equivalent degrees of freedom (EDOF)

- moment matching yields

$$\eta = \frac{2 \left( E\{\hat{\nu}_X^2(\tau_j)\} \right)^2}{\text{var} \{ \hat{\nu}_X^2(\tau_j) \}}$$



## Three Ways to Set $\eta$

1. use large sample theory with appropriate estimates:

$$\hat{\eta}_1 = \frac{M_j \hat{\nu}_X^4(\tau_j)}{\hat{A}_j}$$

2. assume nominal shape for spectral density function of  $X_t$ :

$S_X(f) = hC(f)$ , where  $C(f)$  is known, but  $h$  is not;

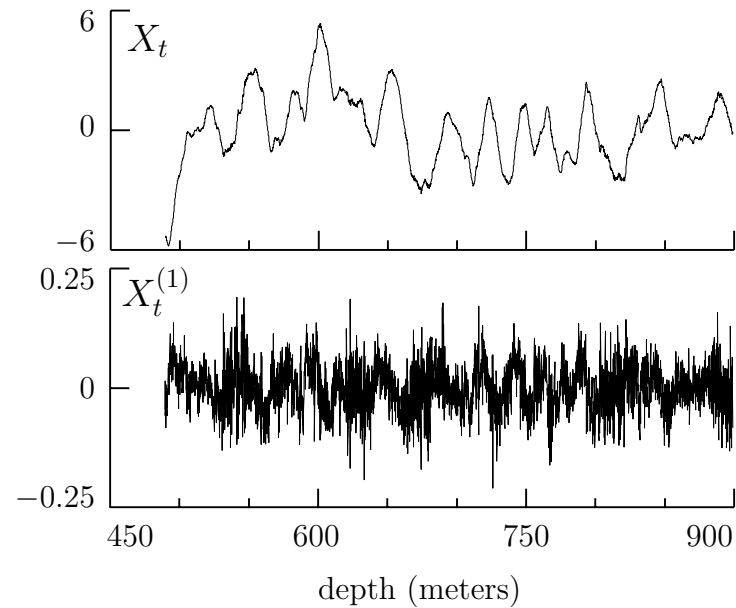
though questionable, get acceptable CIs using

$$\eta_2 = \frac{2 \left( \sum_{k=1}^{\lfloor (M_j-1)/2 \rfloor} C_j(f_k) \right)^2}{\sum_{k=1}^{\lfloor (M_j-1)/2 \rfloor} C_j^2(f_k)}$$

3. make an assumption about the effect of wavelet filter on  $X_t$  to obtain simple (but effective!) approximation

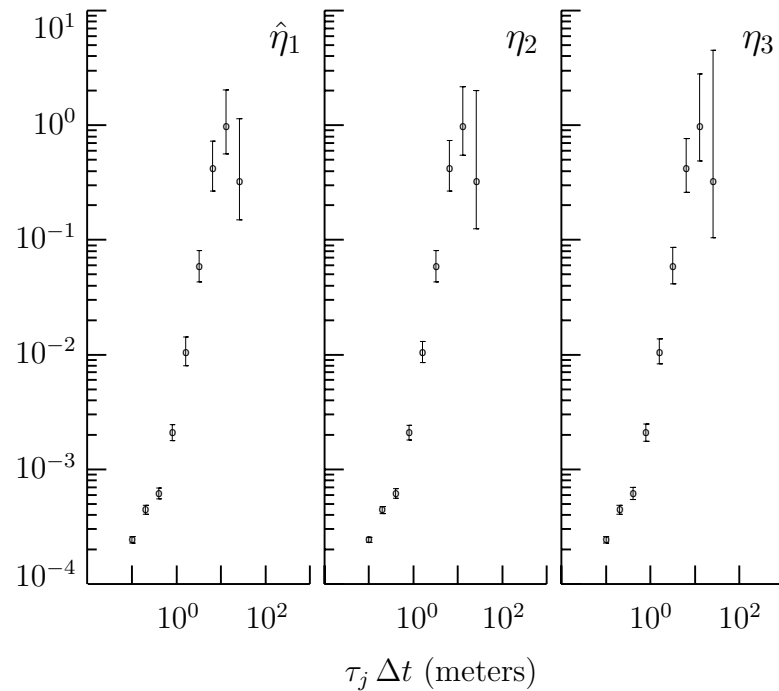
$$\eta_3 = \max\{M_j/2^j, 1\}$$

## Example: Vertical Shear in the Ocean: I



- top plot: vertical shear measurements  $X_t$
- bottom: backward differences  $X_t^{(1)}$

## Example: Vertical Shear in the Ocean: II



- wavelet variance estimates based upon Daubechies wavelet with  $L_1 = 6$ , along with 95% confidence intervals for true wavelet variance with EDOFs determined by  $\hat{\eta}_1$  estimated from data,  $\eta_2$  using a nominal model for  $S_X(\cdot)$  and  $\eta_3 = \max\{M_j/2^j, 1\}$

## Statistical Properties of $\hat{\nu}_X^2(\tau_j)$ (Non-Gaussian)

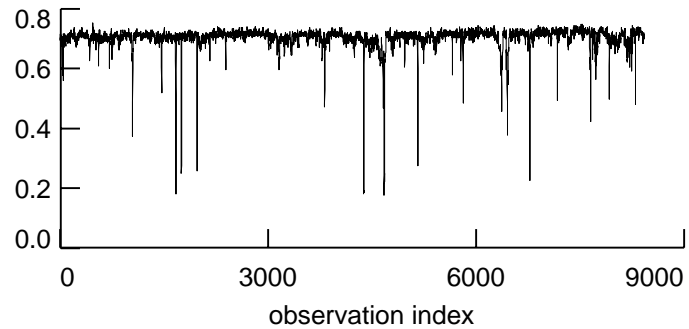
- assume  $\{\overline{W}_{j,t}\}$  strictly stationary process satisfying
  - $E\{\overline{W}_{j,t}\} = 0$  and  $E\{|\overline{W}_{j,t}|^{4+2\delta}\} < \infty$  for some  $\delta > 0$
  - mixing condition  $\alpha_{\overline{W}_{j,t}} = O(1/n^\chi)$ , where

$$\alpha_{\overline{W}_{j,t}} \equiv \sup_{A \in \mathcal{M}_{-\infty}^0, B \in \mathcal{M}_t^\infty} |\mathbf{P}(A \cap B) - \mathbf{P}(A)\mathbf{P}(B)|,$$

$\mathcal{M}_m^n$  is  $\sigma$ -algebra for  $\overline{W}_{j,m}, \dots, \overline{W}_{j,n}$  and  $\chi > (2 + \delta)/\delta$

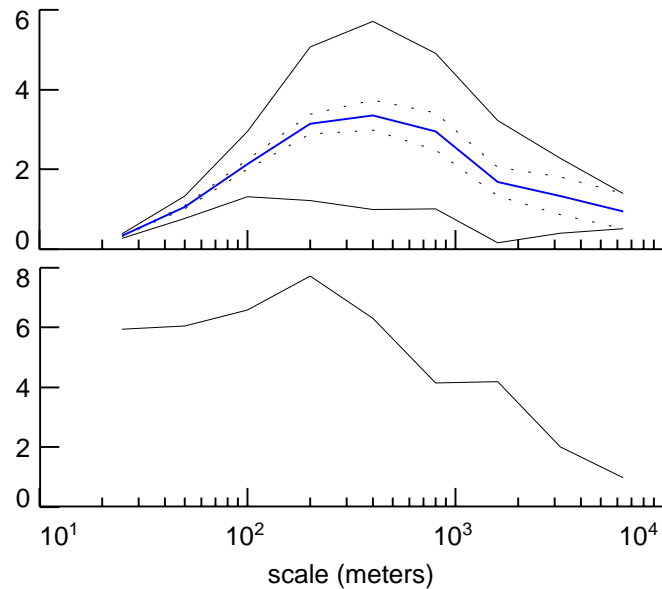
- let  $Z_{j,t} \equiv \overline{W}_{j,t}^2$  have spectral density function (SDF)  $S_{Z_j}(\cdot)$  such that  $0 < S_{Z_j}(0) < \infty$
- $\hat{\nu}_X^2(\tau_j)$  asymptotically normal with mean  $\nu_X^2(\tau_j)$  & large sample variance  $S_{Z_j}(0)/M_j$  (can be estimated using standard SDF estimators such as multitaper or autoregressive estimators)

## Example: Surface Albedo of Spring Pack Ice: I



- data from Beaufort Sea ( $N = 8428$ , sampled every 25 meters)

## Example: Surface Albedo of Spring Pack Ice: II

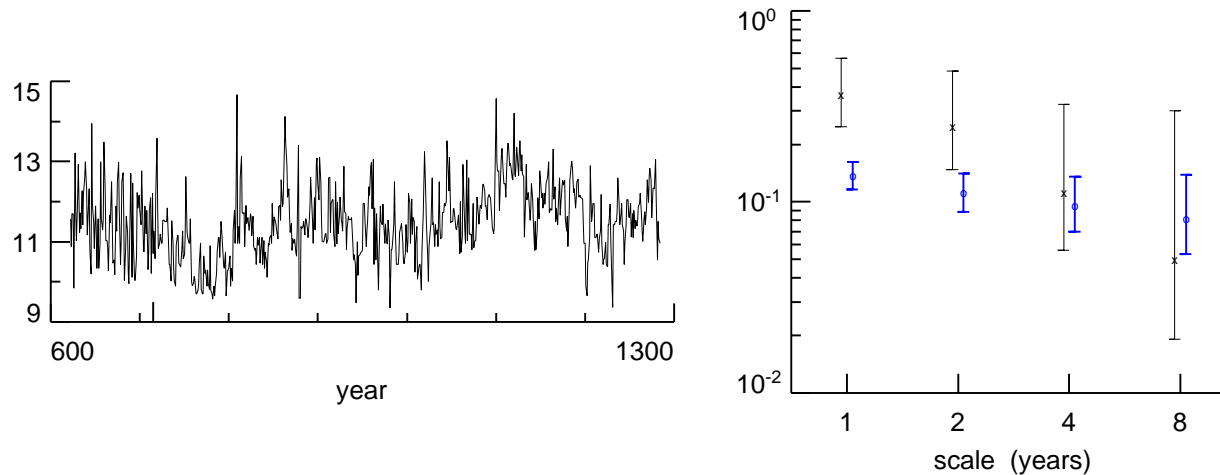


- upper plot: estimated LA(8) wavelet variance (blue curve), along with upper and lower 90% confidence intervals based upon Gaussian (thin dotted curves) and non-Gaussian theory (thin solid)
- lower plot: ratio of estimated non-Gaussian versus Gaussian large sample standard deviations

# Wavelet Variance Analysis of Time Series with Time-Varying Statistical Properties

- each wavelet coefficient  $\widetilde{W}_{j,t}$  formed using portion of  $X_t$
- suppose  $X_t$  associated with actual time  $t_0 + t \Delta t$ 
  - \*  $t_0$  is actual time of first observation  $X_0$
  - \*  $\Delta t$  is spacing between adjacent observations
- suppose  $\tilde{h}_{j,l}$  is least asymmetric Daubechies wavelet
- can associate  $\widetilde{W}_{j,t}$  with an interval of width  $2\tau_j \Delta t$  centered at
$$t_0 + (2^j(t + 1) - 1 - |\nu_j^{(H)}| \bmod N) \Delta t,$$
where, e.g.,  $|\nu_j^{(H)}| = [7(2^j - 1) + 1]/2$  for LA(8) wavelet
- can thus form ‘localized’ wavelet variance analysis (implicitly assumes stationarity or stationary increments locally)

## Example: Annual Minima of Nile River



- left plot: annual minima of Nile River
- bottom: Haar  $\hat{\nu}_X^2(\tau_j)$  before (**x**'s) and after (**o**'s) year 715.5, with 95% confidence intervals based upon  $\chi_{\eta_3}^2$  approximation



## Some Extensions and Ongoing Work

- wavelet cross-covariance and cross-correlation (see references)
- biased estimators of wavelet variance
- unbiased estimator of wavelet variance for ‘gappy’ time series
- extension of notion and estimators to random fields

## Summary

- wavelet variance gives scale-based analysis of variance
- statistical theory worked out for
  - Gaussian processes with stationary backward differences
  - non-Gaussian processes satisfying a mixing condition
- applications include analysis of
  - genome sequences
  - frequency fluctuations in atomic clocks
  - changes in variance of soil properties
  - accumulation of snow fields in polar regions
  - turbulence in atmosphere and ocean
  - regular and semiregular variables stars
- thanks for invitation to speak!!!

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