

# Decline of Arctic Sea-Ice Thickness as Evidenced by Submarine Measurements

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NSF-sponsored collaborative effort with Drew Rothrock,  
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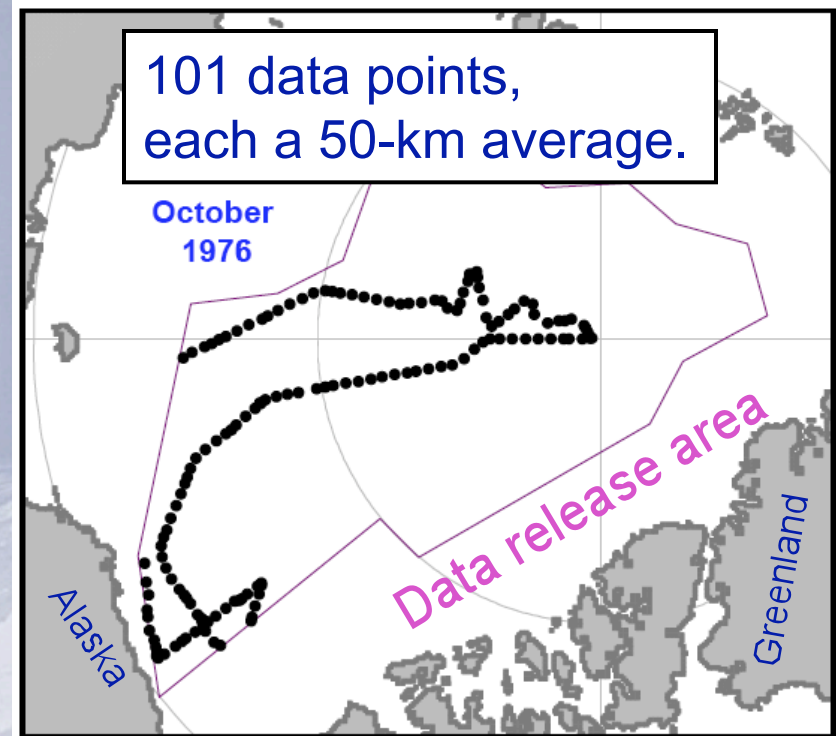
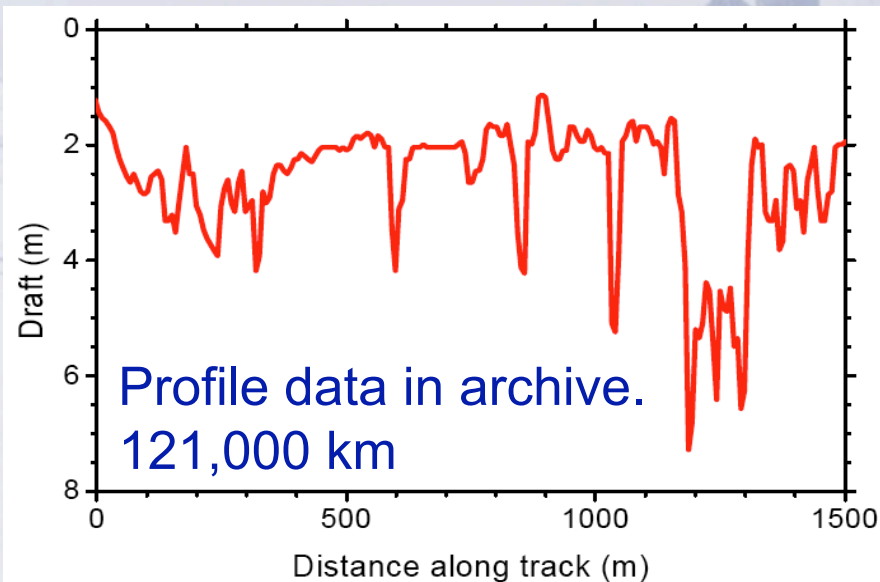
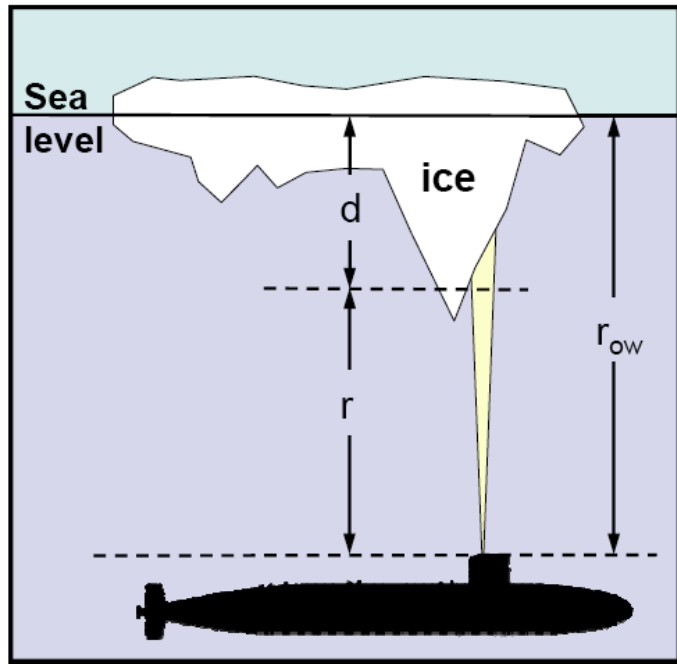
# Overview

- scientific question of interest: has average thickness of Arctic sea ice declined significantly over the past 30+ years?
- thickness can be deduced from draft (submerged portion of sea ice – 93% of ice thickness) as measured by upward-looking sonars on submarines
- previous analyses of submarine data differ from ours because of use of
  - new statistical model for correlation of measurements (incorporates so-called ‘long-range’ dependence)
  - multiple regression analysis to deduce space/time variations
  - newly archived data for submarine cruises from 1975 to 2001 (almost doubling the amount of available data)

## Outline of Talk

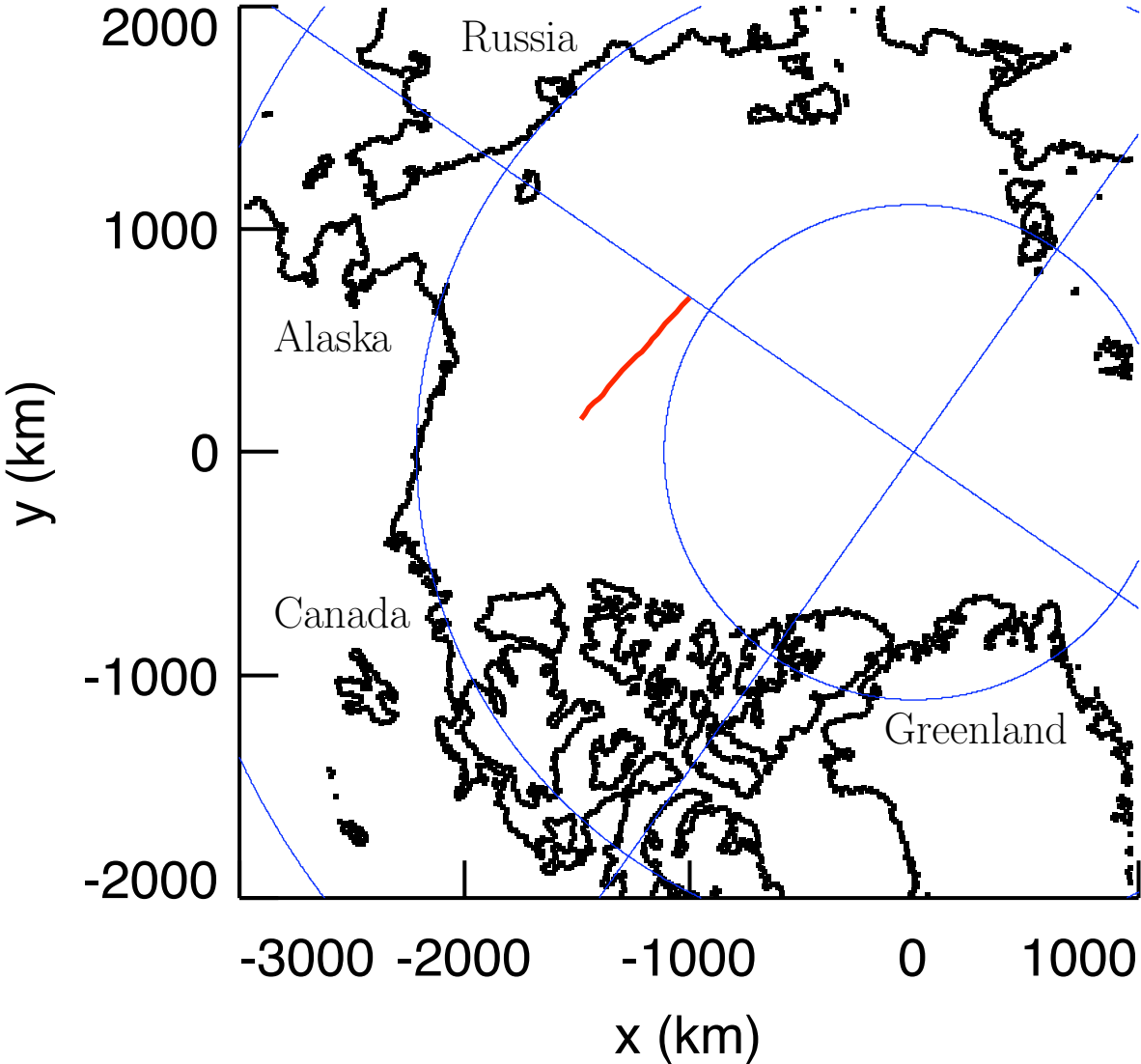
- describe how data were collected
- look at single submarine track to develop model for correlation structure, contrasting properties of two candidate models:
  - first-order autoregressive (AR(1)) process
  - fractionally differenced (FD) process
- discuss how to embed single-track model into overall space/time model
- describe multiple regression model and rationale for fitting model using ordinary least squares rather than generalized least squares
- discuss conclusions that can be drawn from regression analysis

# Ice Draft from Upward-Looking Sonar



(Wensnahan et al., *EOS*, Jan., 2007)

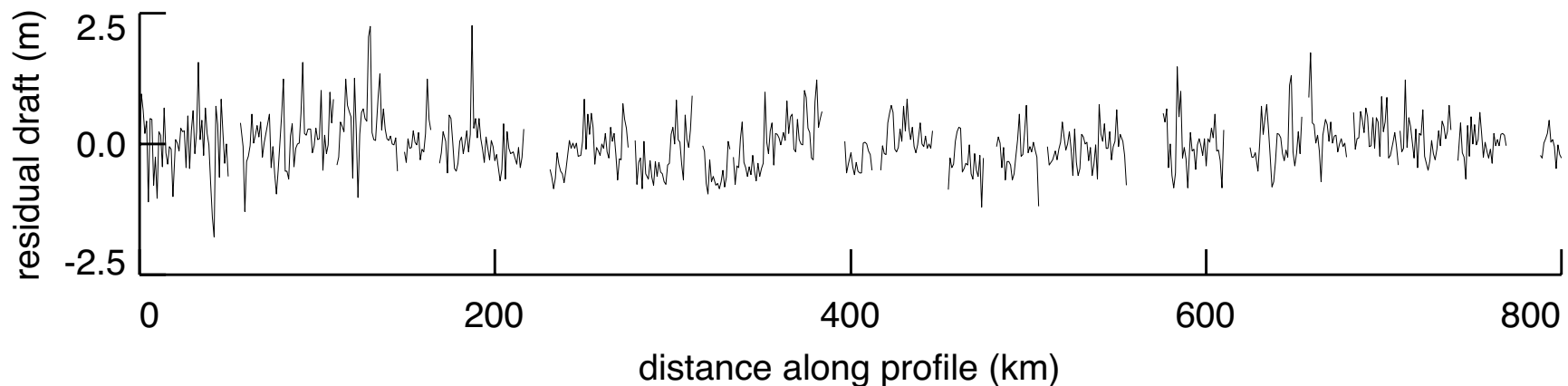
# Map of Arctic Region with **One Submarine Tract**



## Understanding Spatial Correlation

- as submarine moves below ice, returns from sonar provide measurements of ice draft averaged over 1 m patches, which are recorded at 1 m intervals
- when submarine is moving along a tract (straight line), use 1000 consecutive measurements to form 1 km averages  $\overline{H}_{1,n}$ , where  $n$  is the index for a particular average
- later on, will average 50 consecutive nonoverlapping  $\overline{H}_{1,n}$ 's to form 50 km averages – denote these as  $\overline{H}_{50,\mathbf{x}_n,t}$ , where  $\mathbf{x}_n$  is the center of the tract and  $t$  is the associated time ( $\mathbf{x}_n = [0, 0] =$  North Pole, while  $t \in [1975, 2001]$ )
- need to understand spatial covariance properties of  $\overline{H}_{50,\mathbf{x}_n,t}$ , which we can tackle by studying covariance of  $\overline{H}_{1,n}$

## Residual Draft Profile for One Submarine Track



- above comes from track shown on overhead 6 (longest in 1997)
- to study covariance, have subtracted off linear trend (for profiles less than 200 km or so, need only subtract sample mean)
- will now let  $\overline{H}_{1,n}$  denote residual draft profile
- residuals approximately Gaussian (room for improvement?)
- note: lots of gaps in draft profile (631 averages over 803 km)

## Statistical Modeling of Residual Draft Profiles

- simple model of independence for  $\overline{H}_{1,n}$  along profile not viable (e.g., adjacent measurements  $\overline{H}_{1,n}$  and  $\overline{H}_{1,n+1}$  are correlated)
- assume  $\overline{H}_{1,n}$  is a realization of a zero mean Gaussian stationary process (a ‘time’ series with distance replacing ‘time’)
- process fully characterized by its variance  $\sigma_1^2$  and autocorrelation sequence  $\rho_d \equiv E\{\overline{H}_{1,n}\overline{H}_{1,n+d}\}/\sigma_1^2$ , where  $d$  is the distance between measurements (lag) expressed in km
- consider two simple parametric forms for  $\rho_d$  corresponding to
  - first-order autoregressive (AR(1)) process
  - fractionally differenced (FD) process



## First-Order Autoregressive (AR(1)) Processes: I

- process satisfies  $\overline{H}_{1,n} = \phi \overline{H}_{1,n-1} + \epsilon_n$ , where  $|\phi| < 1$ , and  $\epsilon_n$ 's are IID Gaussian with mean 0 and variance  $\sigma_\epsilon^2$
- process can be expressed as

$$\overline{H}_{1,n} = \sum_{j=0}^{\infty} \psi_j \epsilon_{n-j} \quad \text{with} \quad \psi_j = \phi^j$$

- $\rho_d = \phi^{|d|}$ , i.e., ‘short-range’ correlation in that it disappears rapidly (exponentially) with increasing distance
- related to a first-order stochastic differential equation with ‘correlation time’ dictated by  $\phi$  (widely used in climate research)
- given gappy draft profiles, can estimate  $\phi$  and  $\sigma_\epsilon^2$  using maximum likelihood (Jones, 1980), yielding  $\hat{\phi} \doteq 0.36 (\pm 0.04)$

## Fractionally Differences (FD) Processes

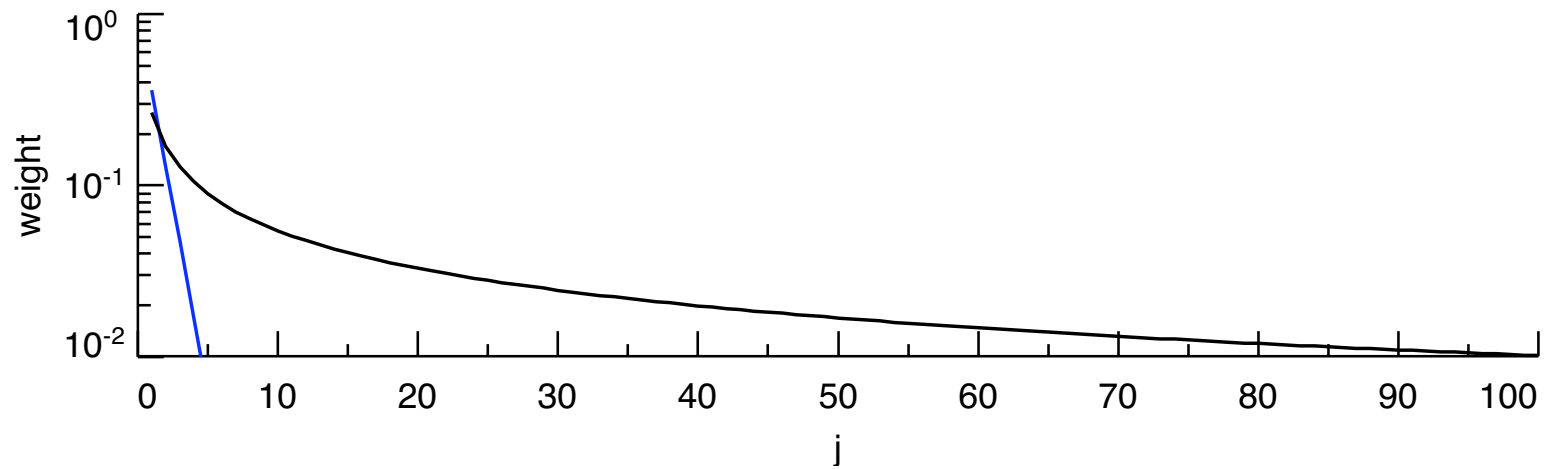
- process can be expressed as

$$\overline{H}_{1,n} = \sum_{j=0}^{\infty} \psi_j \epsilon_{n-j} \quad \text{with} \quad \psi_j = \frac{\Gamma(j + \delta)}{\Gamma(j + 1)\Gamma(\delta)},$$

where  $|\delta| < 1/2$ , and  $\epsilon_n$  is as before

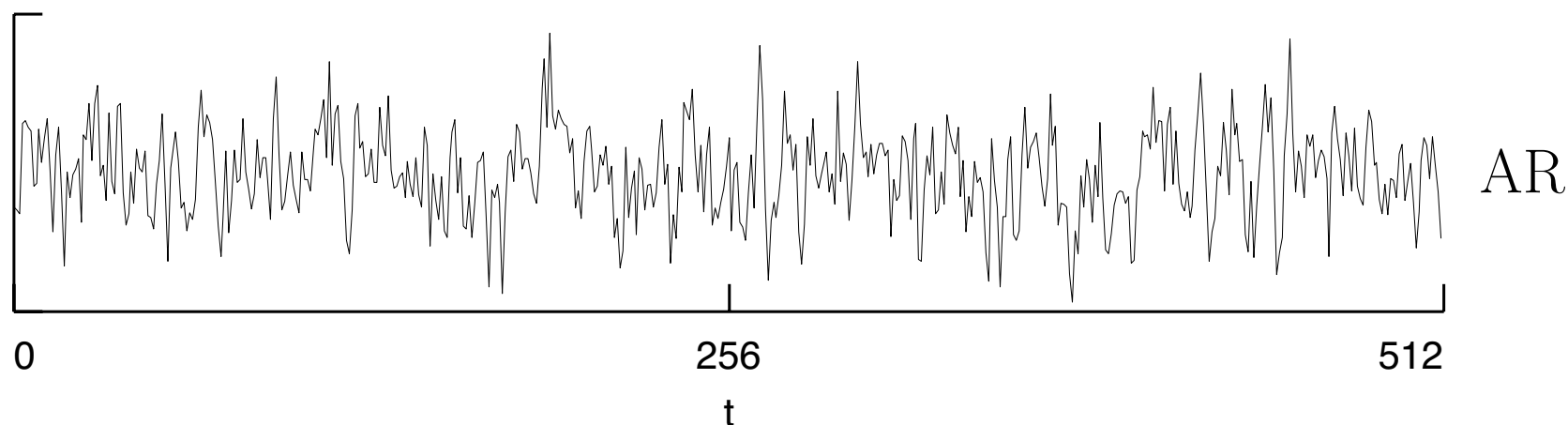
- $\rho_d \approx C|d|^{2\delta-1}$ , i.e., much slower decay rate than for AR(1)
- related to average of many first-order stochastic differential equations with different correlation times (popular model for ‘long-range’ or ‘long-memory’ dependence)
- given gappy profiles, can estimate  $\delta$  and  $\sigma_\epsilon^2$  using maximum likelihood (Palma & Chan, 1997), yielding  $\hat{\delta} \doteq 0.27 (\pm 0.03)$
- Q: how do these two models compare?

## Qualitative Comparison I: $\psi$ Weights



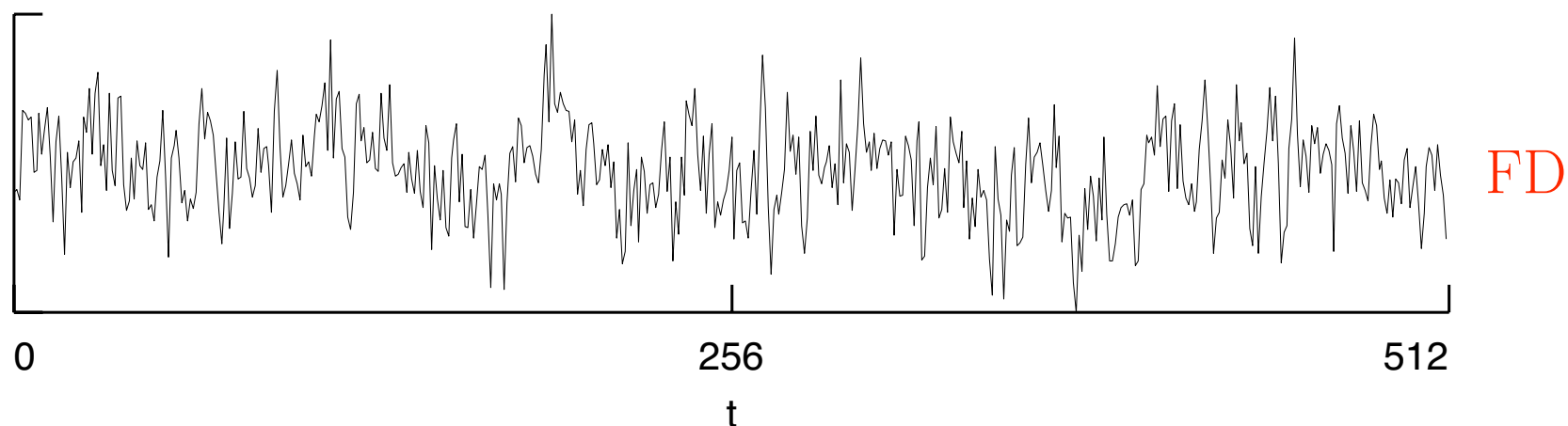
- weights  $\psi_j$  used to create AR with  $\phi = 0.36$  (blue curve) and FD with  $\delta = 0.27$  (black curve) processes from a weighted average of white noise

## Qualitative Comparison II: Simulated Draft Profiles



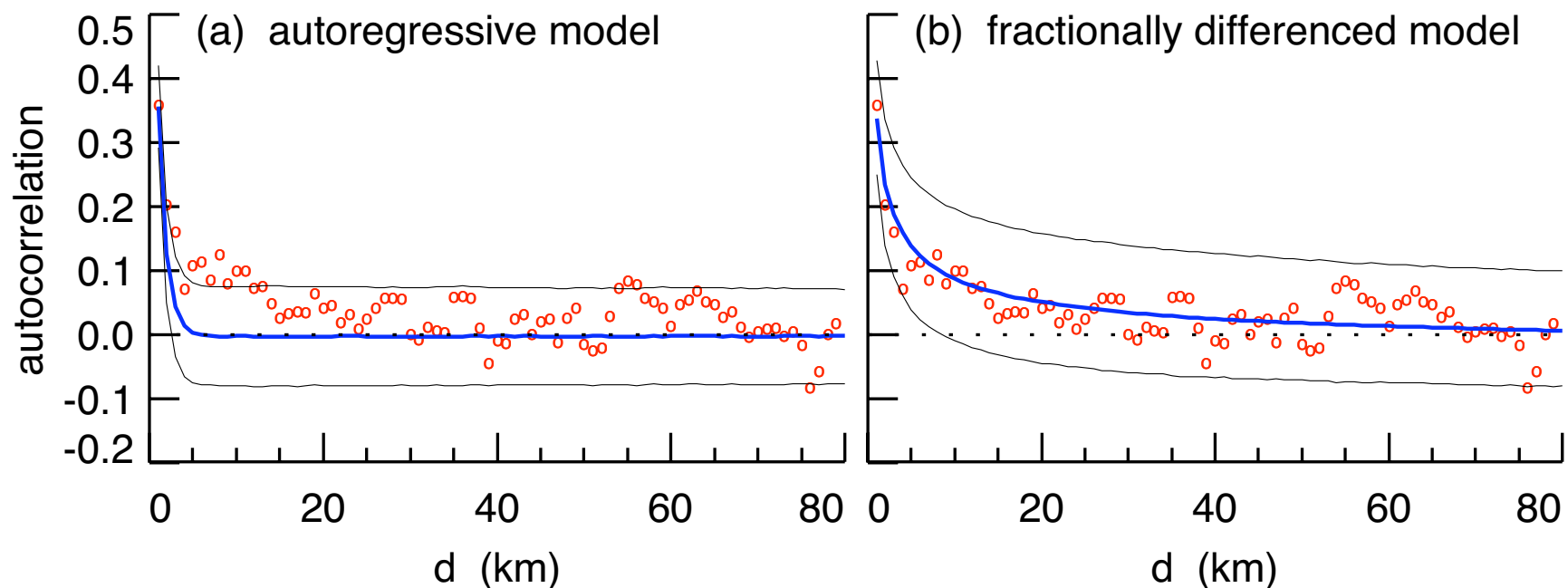
- consider simulated AR ( $\phi = 0.36$ ) & **FD** ( $\delta = 0.27$ ) profiles
- ‘exact’ simulations formed using circulant embedding technique that maps same 1024 IID Gaussian deviates to both profiles (Davies and Harte, 1987; Craigmile, 2003)

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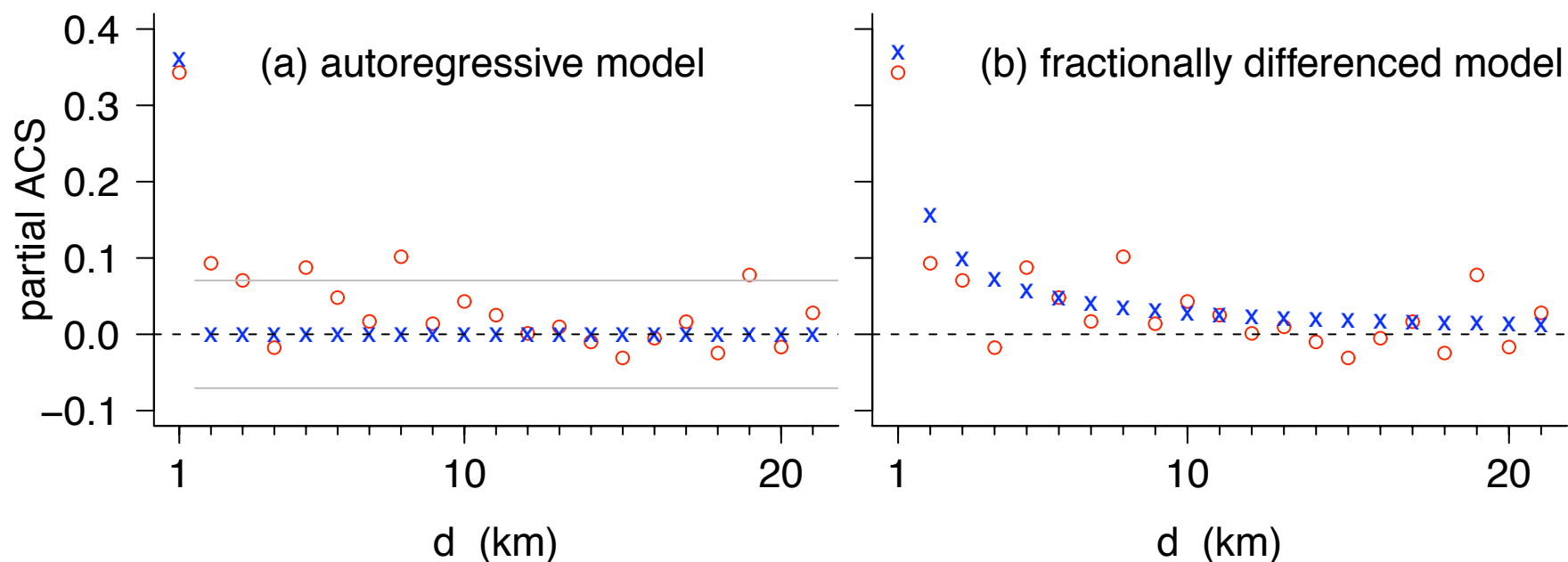
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## Third Comparison: Autocorrelation Sequences



- sample (circles) and theoretical sequences (middle curves)
- upper and lower curves are 95% pointwise confidence intervals for  $\rho_d$  assuming relevant model (AR or FD)

## Fourth Comparison: Partial Autocorrelations



- sample (circles) and theoretical sequences (x's)
- parallel gray lines in (a) are limits between which approximately 95% of samples  $\hat{\phi}_{d,d}$  at lags  $d \geq 2$  should fall under assumption that AR(1) model is correct

## PACS-Based Portmanteau Test for AR(1) Process

- can test null hypothesis that  $\overline{H}_{1,n}$  comes from a Gaussian AR(1) process versus nonspecific alternative hypothesis of non-white Gaussian stationary process
- test is variation on standard portmanteau test for white noise (using sample autocorrelation sequence) and is given by

$$T \equiv N \sum_{d=2}^{K+1} \hat{\phi}_{d,d}^2$$

- can reject null if  $T$  is ‘too large’ in comparison to upper percentage points of  $\chi^2$  distribution with  $K$  degrees of freedom
- $\hat{\alpha}$  (observed level of significance) is  $< 0.014$  for both  $K = 10$  and  $K = 20$ , so AR(1) hypothesis unlikely to be true



## Fifth Comparison: Variance of Sample Means

- given  $\bar{H}_{1,n}$ ,  $n = 0, \dots, N - 1$ , consider statistical properties of length  $L$  averages

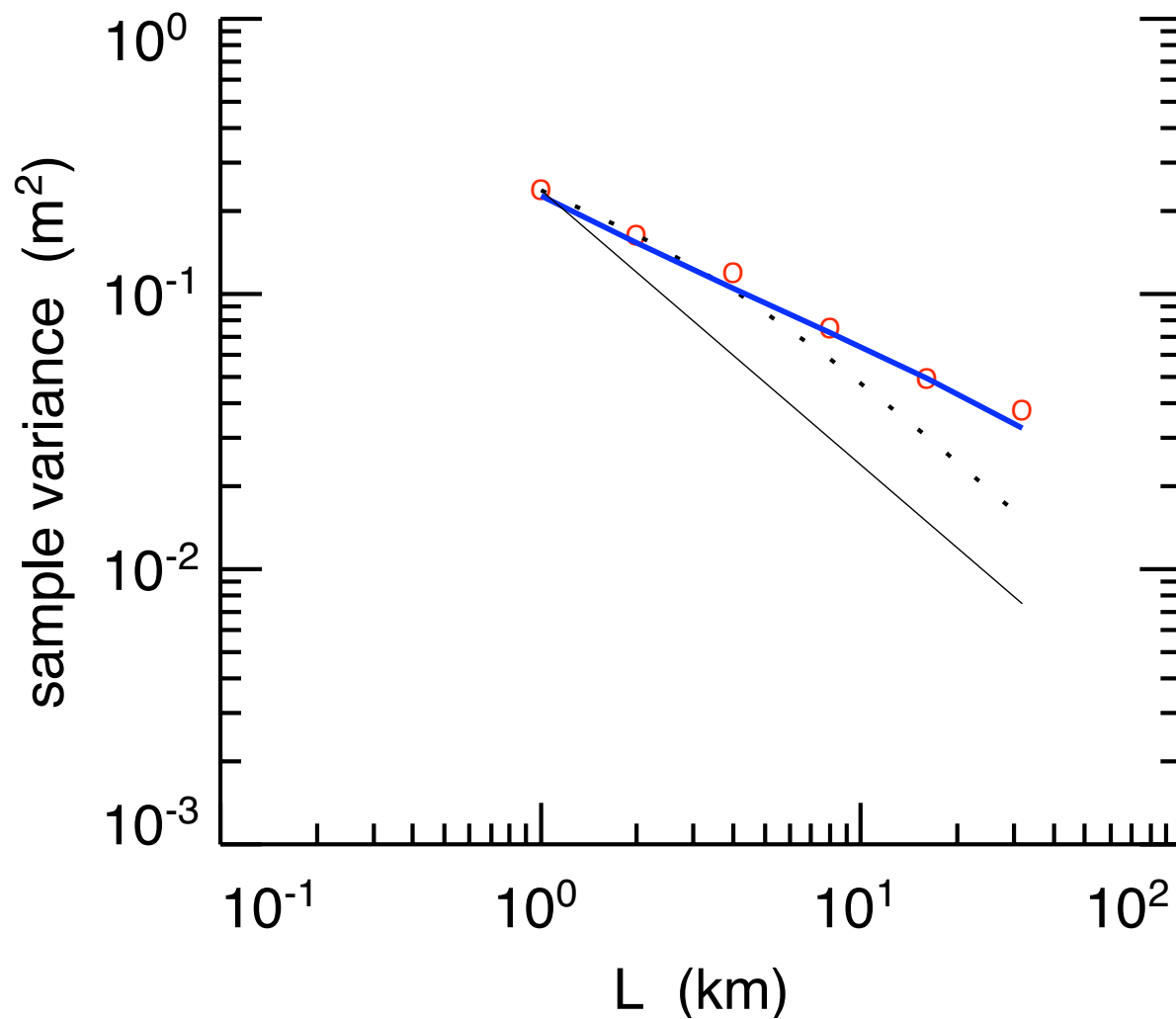
$$\bar{H}_{L,m} = \frac{1}{L} \sum_{l=0}^{L-1} \bar{H}_{1,mL+l}, \quad m = 0, 1, \dots, \lfloor N/L \rfloor - 1$$

- let  $\sigma_L^2 = \text{var} \{ \bar{H}_{L,m} \}$
- for AR and FD models, have

$$\sigma_L^2 \approx \sigma_1^2 \times \frac{1 + \phi}{1 - \phi} \times L^{-1} \quad \text{and} \quad \sigma_L^2 \approx \sigma_1^2 \times \frac{\Gamma(1 - \delta)}{(2\delta + 1)\Gamma(1 + \delta)} \times L^{-1+2\delta}$$

- can compare sample estimates  $\hat{\sigma}_L^2$  with  $E\{\hat{\sigma}_L^2\}$  for various  $L$

# Sample $\hat{\sigma}_L^2$ (Circles) and Theoretical $\sigma_L^2$ versus $L$

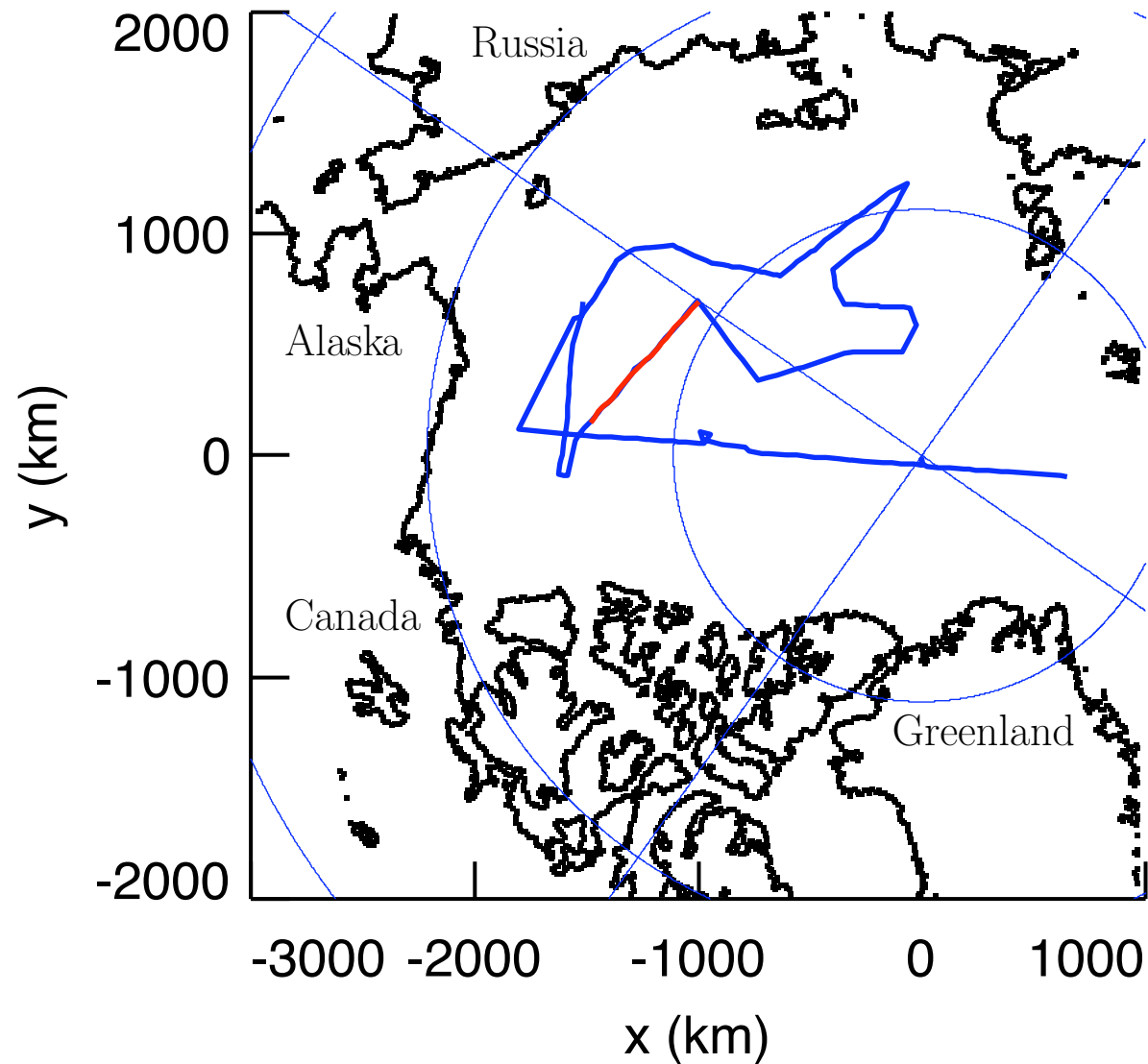


blue: FD

dotted: AR(1)

solid: white noise

# Map of Arctic Region with Tracks Taken in 1997





## Spatial Model for One Kilometer Averages

- analysis of additional profiles in 1997 and other years indicates FD model with  $\delta = 0.27$  is good overall choice
- will now reindex  $\bar{H}_{1,n}$  using a 2D vector  $\mathbf{x}_n$  indicating the location of the 1 km average (needed for dealing with data from multiple tracks)
- can regard  $\bar{H}_{1,\mathbf{x}_n}$  as samples from a stationary and isotropic two-dimensional (2D) random process with covariances given by

$$\text{cov} \{ \bar{H}_{1,\mathbf{x}_n}, \bar{H}_{1,\mathbf{x}_n+\mathbf{d}} \} \equiv \sigma_1^2 \times \frac{\Gamma(|\mathbf{d}| + \delta)\Gamma(1 - \delta)}{\Gamma(|\mathbf{d}| + 1 - \delta)\Gamma(\delta)},$$

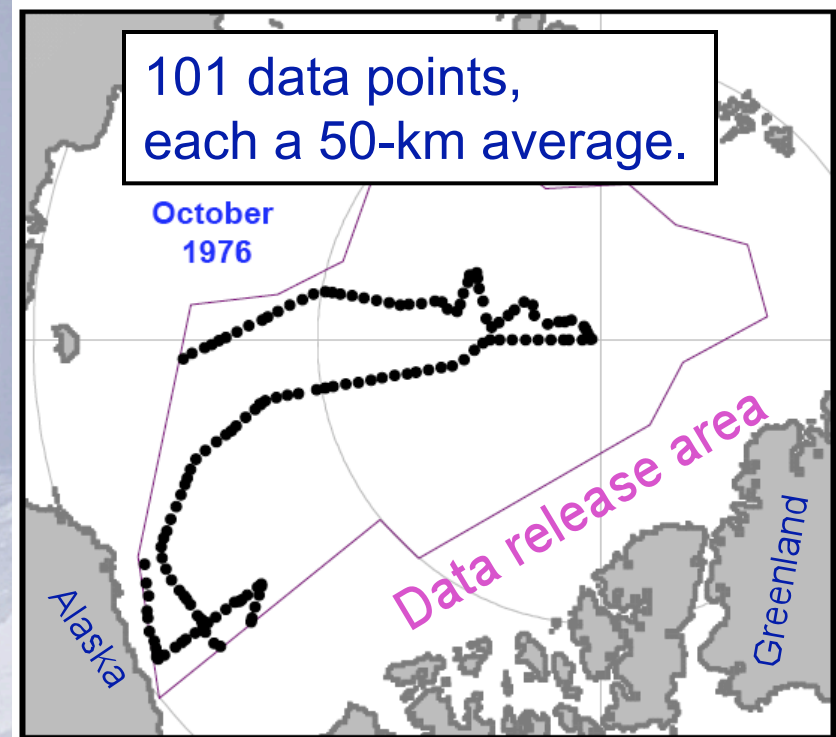
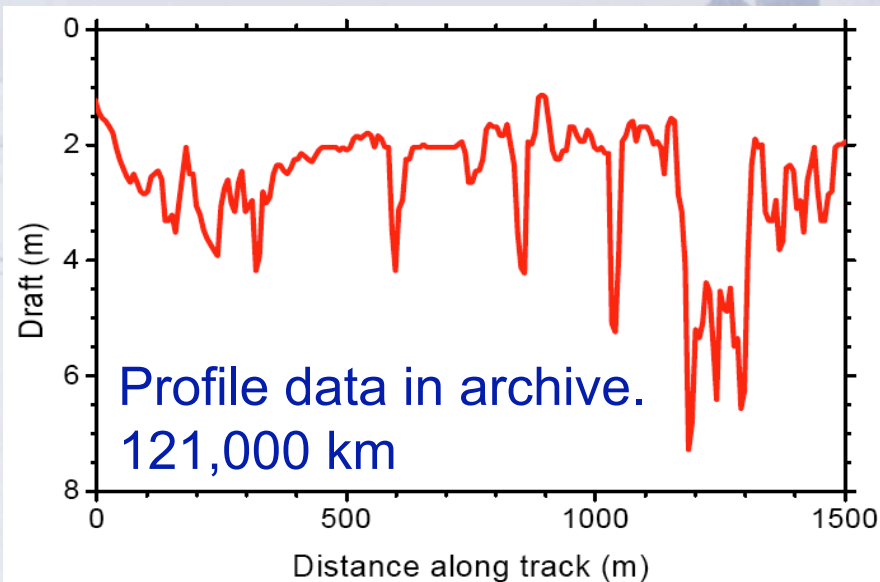
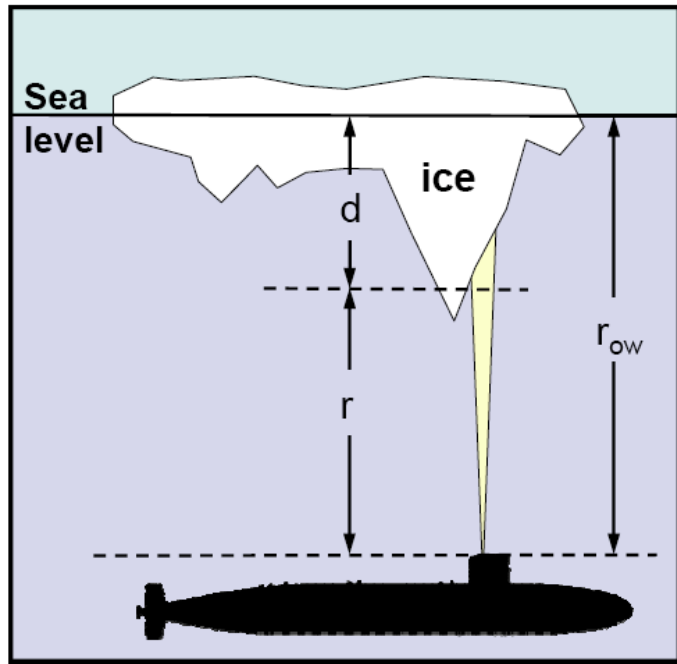
where  $\mathbf{d}$  is an arbitrary 2D vector, and  $|\mathbf{d}|$  is its Euclidean norm

- 1D tracks through this 2D process yield an FD( $\delta$ ) process

## Fifty Kilometer Averages

- to reduce computational burden, combined 1 km averages into 50 km averages, yielding  $\overline{H}_{50, \mathbf{x}_n}$
- assumed form for  $\text{cov} \{ \overline{H}_{1, \mathbf{x}_n}, \overline{H}_{1, \mathbf{x}_n + \mathbf{d}} \}$  can be used to deduce  $\text{cov} \{ \overline{H}_{50, \mathbf{x}_n}, \overline{H}_{50, \mathbf{x}_n + \mathbf{d}} \}$

# Ice Draft from Upward-Looking Sonar



(Wensnahan et al., *EOS*, Jan., 2007)

## Multiple Regression Model: I

- let  $\overline{H}_{50, \mathbf{x}_n, t}$  represent average of 1 km measurements taken at location  $\mathbf{x}_n$  and time  $t$  ( $\mathbf{x}_n = [0, 0] = \text{Pole}$  &  $t \in [1975, 2001]$ )
- let  $\tau$  represent the time of year (i.e.,  $\tau = t \bmod 1$ )
- assume simple model

$$\overline{H}_{50, \mathbf{x}_n, t} = C + I(t) + A(\tau) + S(\mathbf{x}_n) + \epsilon_{\mathbf{x}_n, t},$$

where

- $C$  is a constant
- $I(t)$  is the interannual variation
- $A(\tau)$  is the annual cycle
- $S(\mathbf{x}_n)$  is the spatial field
- $\epsilon_{\mathbf{x}_n, t}$  is an error term dictated by FD model within a given season (different seasons/years assumed independent)



## Multiple Regression Model: II

- assumed form for interannual variation  $I(t)$  is

$$I(t) = I_1(t - 1988) + I_2(t - 1988)^2 + I_3(t - 1988)^3,$$

where  $I_1$ ,  $I_2$  and  $I_3$  are parameters to be estimated (experimented with other polynomials, but cubic is adequate)

- assumed form for annual cycle is

$$A(\tau) = A_s \sin(2\pi\tau) + A_c \cos(2\pi\tau) = A \cos(2\pi[\tau - \tau_{\max}]),$$

where  $A_s$  and  $A_c$  are parameters to be estimated, from which  $A$  and  $\tau_{\max}$  can be deduced (experimented with adding terms with frequencies at harmonics of annual cycle, but simple form is adequate)

## Multiple Regression Model: III

- letting  $\mathbf{x}_n = [x, y]^T$ , assumed form for spatial field  $S(\mathbf{x}_n)$  is

$$\begin{aligned} S(\mathbf{x}_n) = & S_{10}x + S_{01}y \\ & + S_{20}x^2 + S_{11}xy + S_{02}y^2 \\ & + S_{30}x^3 + S_{21}x^2y + S_{12}xy^2 + S_{03}y^3 \\ & + S_{40}x^4 + S_{31}x^3y + S_{22}x^2y^2 + S_{13}xy^3 + S_{04}y^4 \\ & + S_{50}x^5 + S_{41}x^4y + S_{32}x^3y^2 + S_{23}x^2y^3 + S_{14}xy^4 + S_{05}y^5, \end{aligned}$$

where  $S_{ij}$ 's are parameters to be estimated (experimented with 6th order polynomials, but  $t$ -tests say 5th order is adequate)

- within a given season and year, error term  $\epsilon_{\mathbf{x}_n,t}$  has a covariance structure dictated by FD model
- $\epsilon_{\mathbf{x}_n,t}$ 's from different seasons or years are assumed to be independent (reasonable assumption, based upon ice physics)

## Fitting Multiple Regression Model: I

- used ordinary least squares (OLS) to fit model, even though correlated errors recommends generalized least squares (GLS)
- to see rationale, recall relationship between OLS & GLS
- write regression model as  $\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$ , with  $\boldsymbol{\epsilon} \stackrel{d}{=} \mathcal{N}(\mathbf{0}, \Sigma_{\boldsymbol{\epsilon}})$
- OLS estimator is  $\hat{\boldsymbol{\beta}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y}$
- let  $\Sigma_{\boldsymbol{\epsilon}}^{1/2}$  be ‘square root’ of  $\Sigma_{\boldsymbol{\epsilon}}$ , i.e.,  $\Sigma_{\boldsymbol{\epsilon}}^{1/2} \Sigma_{\boldsymbol{\epsilon}}^{1/2} = \Sigma_{\boldsymbol{\epsilon}}$ , and use its inverse  $\Sigma_{\boldsymbol{\epsilon}}^{-1/2}$  to transform regression model:

$$\Sigma_{\boldsymbol{\epsilon}}^{-1/2} \mathbf{Y} = \Sigma_{\boldsymbol{\epsilon}}^{-1/2} \mathbf{X} \boldsymbol{\beta} + \Sigma_{\boldsymbol{\epsilon}}^{-1/2} \boldsymbol{\epsilon}, \text{ rewritten as } \tilde{\mathbf{Y}} = \tilde{\mathbf{X}} \boldsymbol{\beta} + \tilde{\boldsymbol{\epsilon}}$$

- OLS estimator  $\tilde{\boldsymbol{\beta}}$  of  $\boldsymbol{\beta}$  in transformed model is GLS estimator for original model:

$$\tilde{\boldsymbol{\beta}} = (\tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \tilde{\mathbf{Y}} = (\mathbf{X}^T \Sigma_{\boldsymbol{\epsilon}}^{-1} \mathbf{X})^{-1} \mathbf{X}^T \Sigma_{\boldsymbol{\epsilon}}^{-1} \mathbf{Y}$$

## Fitting Multiple Regression Model: II

- in general,  $\mathbf{Y}^T\mathbf{Y} \neq \tilde{\mathbf{Y}}^T\tilde{\mathbf{Y}} = \mathbf{Y}^T\Sigma_{\epsilon}^{-1}\mathbf{Y}$ ; i.e., total sums of squares in original and transformed spaces are not equal
- portion of sum of squares explained by transformed model cannot be related directly to sum of squares for original model
- through study of measurement process, have estimate of variance of measurement errors in observations
- want to relate this variance estimate to sum of squares due to error in regression model; i.e., can unexplained variability be chalked up to just measurement errors?
- thus cannot state an ‘error budget’ using transformed model
- standard deviation of OLS-estimated parameters only 5% greater on the average than those for GLS

## Interannual Variation $I(t)$ : I

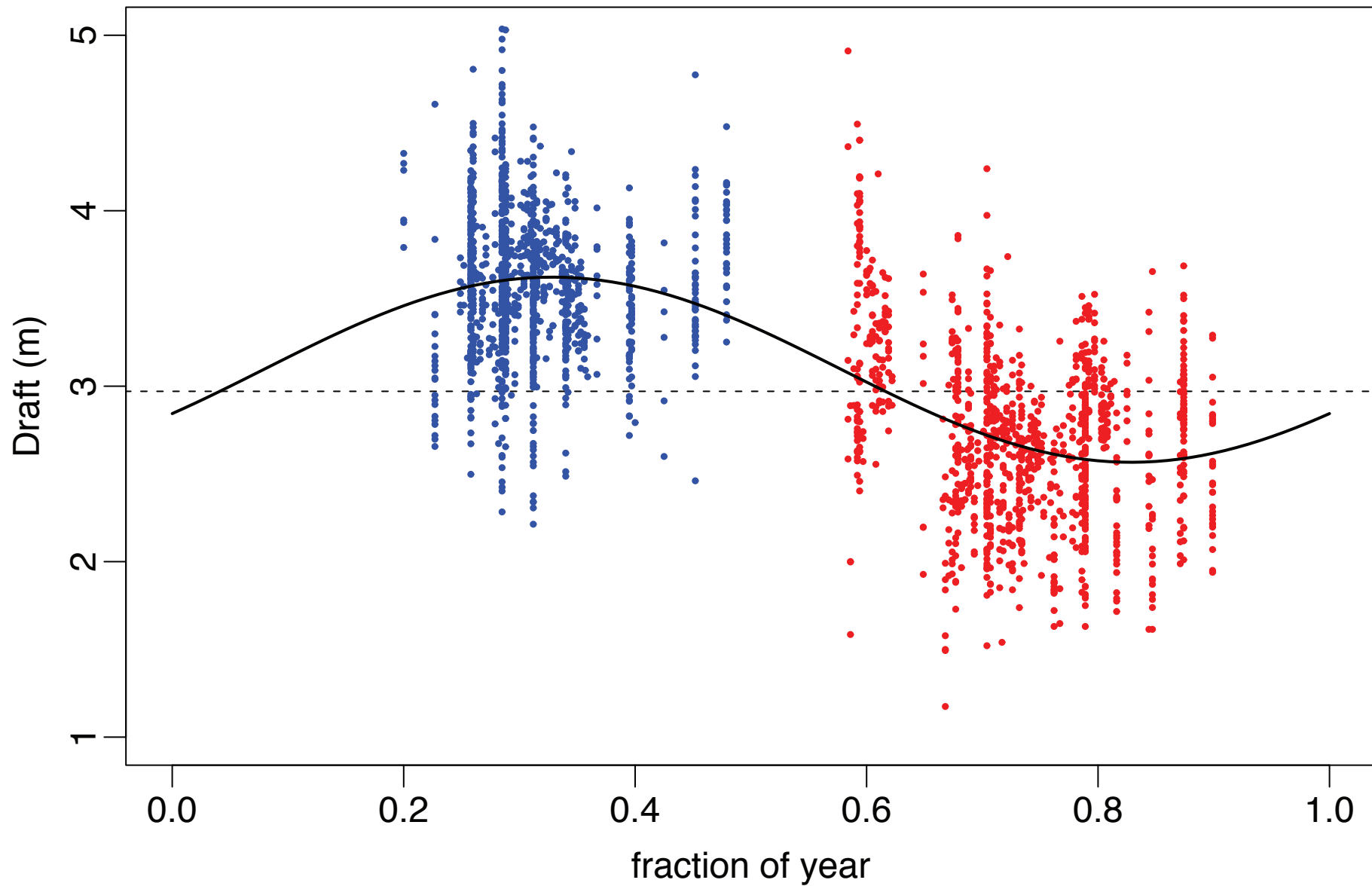
- interannual variation  $I(t)$  is a cubic polynomial
- residuals shown after addition to mean draft and fitted  $I(t)$  (blue for January to June data, red for rest of year)
- change from 1981 to 2000 is  $-1.13$  m
- steepest decline ( $-0.08$  m/yr) occurred in 1991
- no recovery by 2000
- much fuller data set strengthens previous results (Rothrock *et al.*, 1999, and Tucker *et al.*, 2001)



## Annual Cycle $A(\tau)$ : I

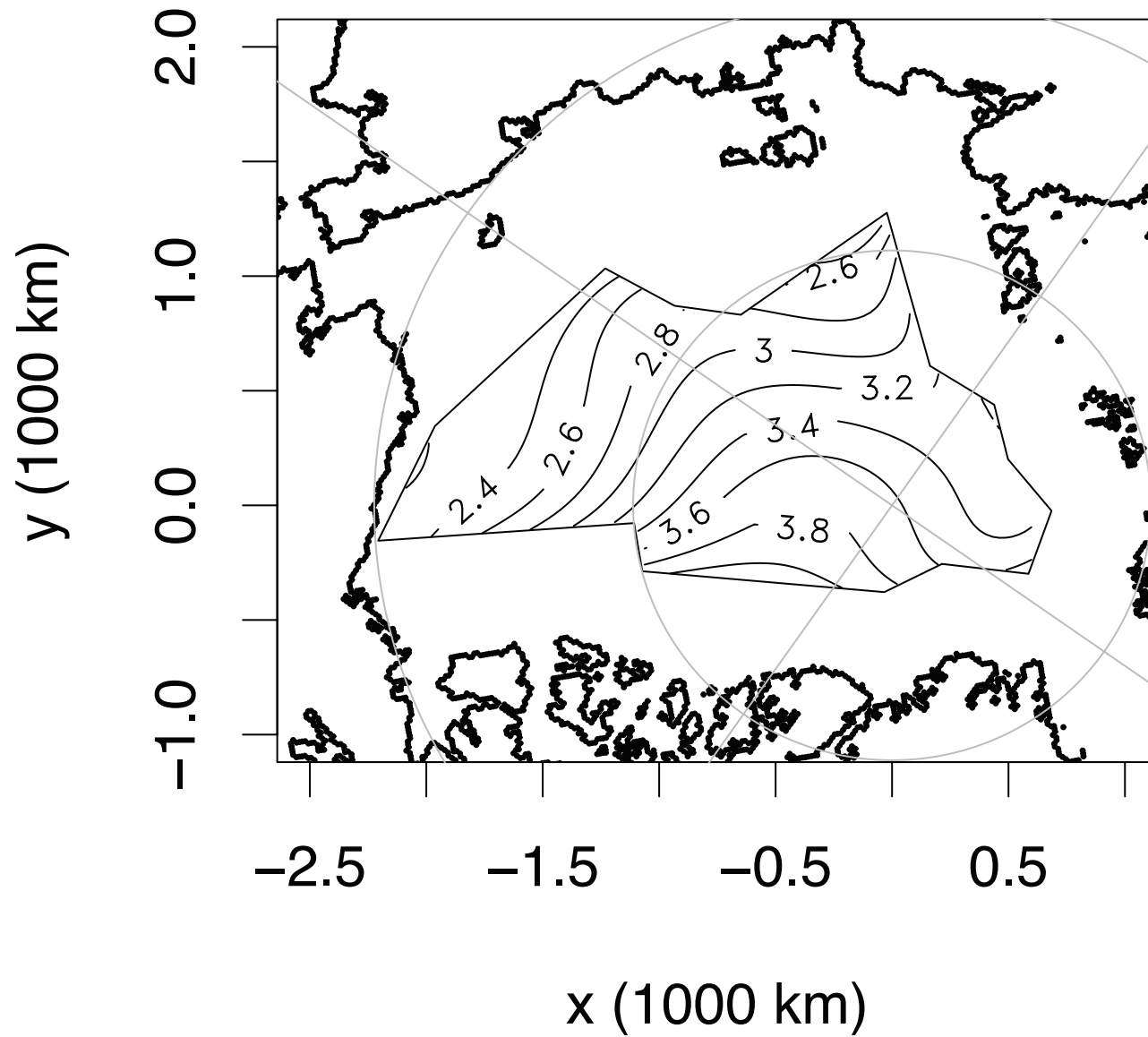
- annual cycle  $A(\tau)$  is a sinusoid with a period of a year
- residuals shown after addition to mean draft and fitted  $A(\tau)$  (blue for January to June data, red for rest of year)
- maximum (minimum) occurs on 30 April (30 October)
- peak-to-trough amplitude is 1.06 m, which is much larger than what would be expected from thermodynamic annual cycle of thickness of multiyear ice ( $\approx 0.43$  m)
- sea-ice models predict asymmetric annual cycles, suggesting the need for harmonics, but data do not support this need (possibly due to preferential sampling during certain parts of the year)

# Annual Cycle $A(\tau)$ : II





# Spatial Field $S(\mathbf{x}_n)$



## Concluding Remarks

- multiple regression model explains 79% of variance in data (standard deviation is 0.98 m)
- unexplained variance has standard deviation of 0.46 m
- estimated standard deviation of measurement errors is 0.25 m
- improvements ('polishing the cannon ball'):
  - relax assumption of a constant spatial field across time
  - estimate  $\delta$  from spatial data, not from profiles

## Thanks to . . .

- Peter Guttorp for invitation to speak
- colleagues in Seattle area:
  - Drew Rothrock and Mark Wensnahan (Polar Science Center, Applied Physics Laboratory, University of Washington)
  - Tilmann Gneiting (Department of Statistics, University of Washington; now at University of Heidelberg)
  - Alan Thorndike (Department of Physics, University of Puget Sound)
- National Science Foundation (USA) for support (any opinions, findings and conclusions or recommendations expressed in this talk are those of the authors and do not necessarily reflect the views of the National Science Foundation)

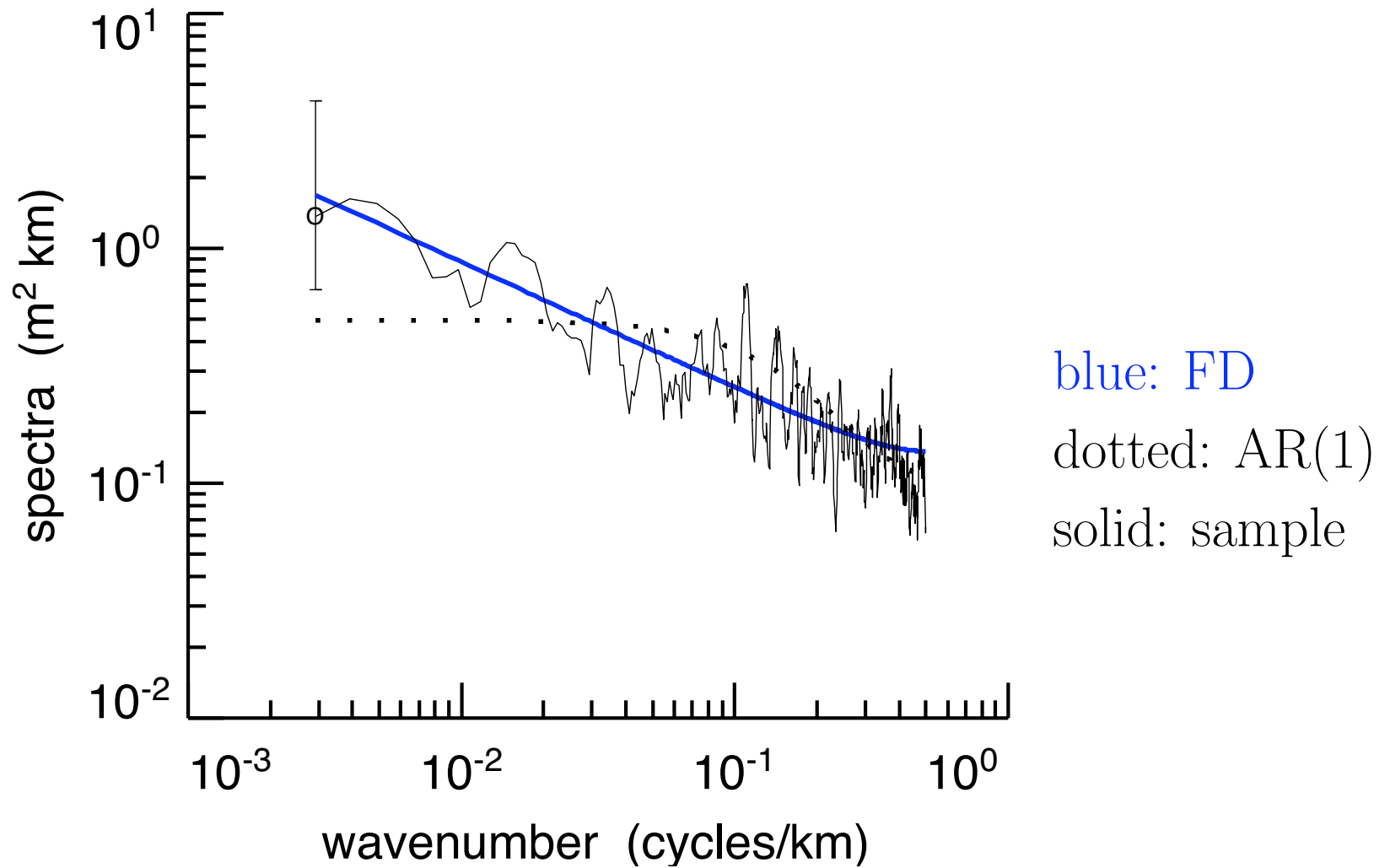
## Main References

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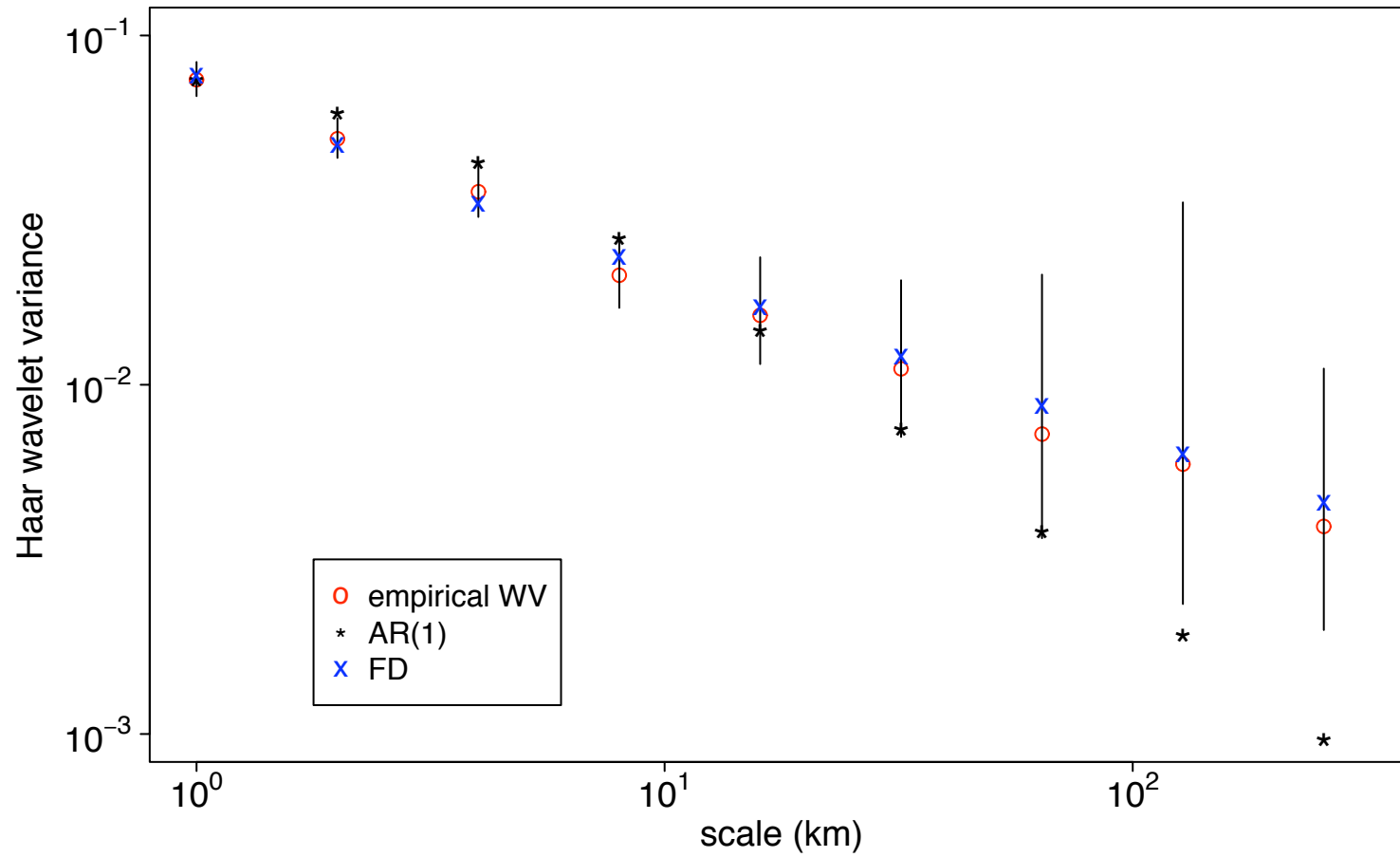
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## Sixth Comparison: Sample and Theoretical Spectra



## Seventh Comparison: Wavelet Variances

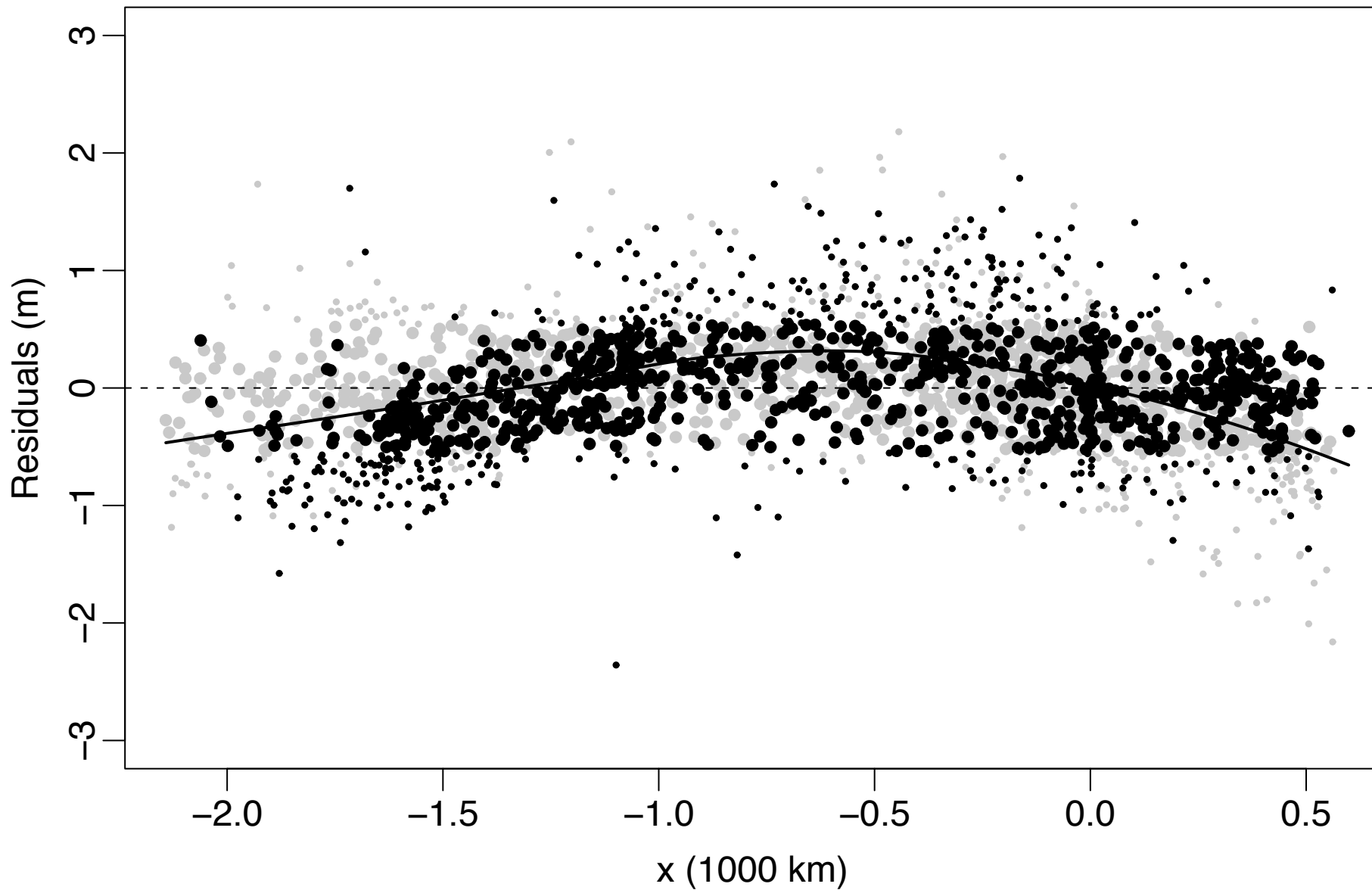


## Spatial Field $S(\mathbf{x}_n)$ : I

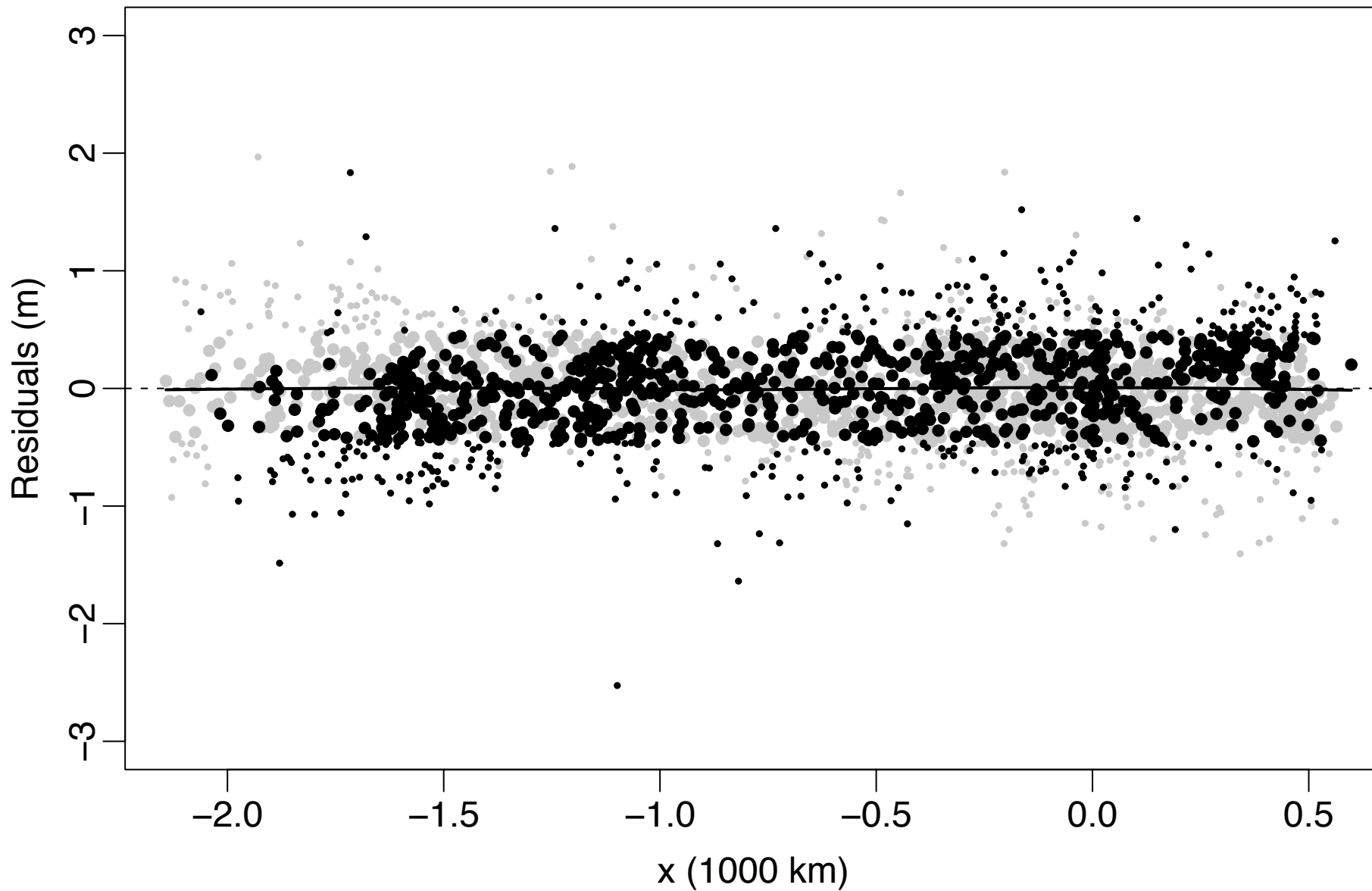
- spatial field  $S(\mathbf{x}_n)$  is a fifth order polynomial in  $x$  &  $y$
- draft varies from 2.2 m near Alaska to just over 4 m near Ellesmere Island
- need for polynomial of higher order than linear indicated by examination of residuals versus  $x$  – obvious structure remaining in linear fit (black for summer/fall, grey for winter/spring)
- corresponding plot of residuals versus  $y$  for linear model doesn't have same obvious structure



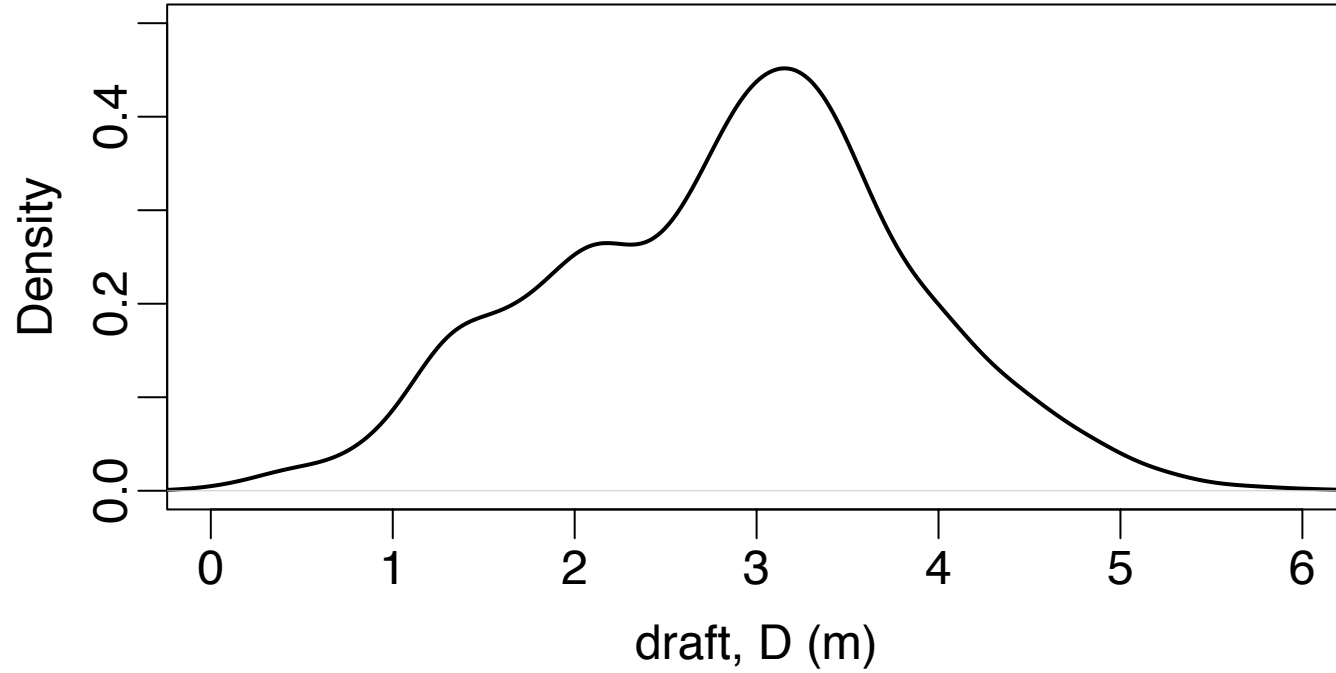
## Spatial Field $S(\mathbf{x}_n)$ : II



# Spatial Field $S(\mathbf{x}_n)$ : IV



## PDF of Observations (SD = 0.99 m)



## PDF of Residuals (SD = 0.46 m)

